



## Development of spatiotemporal land use regression models for PM<sub>2.5</sub> and NO<sub>2</sub> in Chongqing, China, and exposure assessment for the CLIMB study

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### ABSTRACT

Limited research has been conducted in Asia on the association of maternal exposure to ambient air pollution and the increased risk of adverse pregnancy outcomes such as low birth weight and preterm birth. The aim of this study was to develop spatiotemporal land use regression (LUR) models for fine particulate matter (PM<sub>2.5</sub>) and nitrogen dioxide (NO<sub>2</sub>) in Chongqing, China, and to use the models to estimate PM<sub>2.5</sub> and NO<sub>2</sub> exposure for the participants in a randomized trial of complex lipid supplementation (the Complex Lipids In Mothers and Babies (CLIMB) study), before and during pregnancy. Spatiotemporal generalised additive models were developed for 2015–2016 on a daily basis incorporating measurement data from 16 sites, temporal variables on meteorology, and spatial variables produced using a geographical information system. Hold-out validation (HOV) was performed using daily and monthly averaged measurements for 2017 at 17 sites with 4 of the sites in different locations to 2015–16. The PM<sub>2.5</sub> spatiotemporal model had good overall predictive ability (daily HOV correlation (COR)-R<sup>2</sup> = 0.75 and HOV mean-squared-error (MSE)-R<sup>2</sup> = 0.69; monthly HOV COR-R<sup>2</sup> = 0.87 and HOV MSE-R<sup>2</sup> = 0.76). The NO<sub>2</sub> spatiotemporal model estimates had moderate-to-good correlation with measurements (daily HOV COR-R<sup>2</sup> = 0.44; monthly HOV COR-R<sup>2</sup> = 0.65), but estimates were subject to bias (daily HOV MSE-R<sup>2</sup> = 0.24; monthly HOV MSE-R<sup>2</sup> = -0.02). On this basis, we recommend that PM<sub>2.5</sub> models are used for predicting absolute exposure and NO<sub>2</sub> models are used for relative ranking of exposures.

### 1. Introduction

Particulate matter less than 2.5 μm in diameter (PM<sub>2.5</sub>) and nitrogen dioxide (NO<sub>2</sub>) exposure during pregnancy increases the risk of adverse pregnancy outcomes such as low birth weight (Pedersen et al., 2013) and small for gestational age (Stieb et al., 2016). Exposure to PM<sub>2.5</sub> is particularly harmful since its small size allows for deposition deep in the lungs where it exerts systemic damage either indirectly, due to respiratory-mediated release of inflammatory markers (Suwa et al., 2002), or directly through diffusion into the bloodstream and deposition around the body (Nemmar et al., 2002). The relationship of maternal air pollution exposure and adverse pregnancy outcomes has been firmly

established by major studies conducted in North America and Europe (Brauer et al., 2008; Pedersen et al., 2013a; Stieb et al., 2016). However, relatively little research has been conducted in Asia (Li et al., 2020). To conduct epidemiological studies, methods for individual exposure estimation are required.

In the absence of detailed emissions inventories for dispersion modelling, land use regression (LUR) models are commonly used in epidemiological studies for air pollutant exposure estimation (Hoek et al., 2008). LUR models are trained and validated against measured pollutant concentrations using variables generated from a geographic information system (GIS), such as distance to nearest source, road network density, land use, terrain and population density, to predict the

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concentrations at residential locations. Models of annual average concentrations can be developed using widely available spatial data and can capture the fine scale variability in air pollution concentrations (De Hoogh et al., 2014). For use in pregnancy cohort studies, where sub-annual exposure periods are required, LUR models have been developed to account for both the spatial and temporal variation in pollutant concentrations (Barratt et al., 2018; Shi et al., 2018; Xu et al., 2019; Zhang et al., 2020). In China, various techniques have been used to develop LUR models of differing temporal resolution. Tian et al. (2019) and Kong and Tian (2020), for example, developed separate LUR models for different seasons. Xu et al. (2019) used temporal trends in air pollution concentration measurements to develop a model capable of predicting two-week averages. Models with daily temporal resolution have also been developed. Barratt et al. (2018), for example, used air quality monitoring campaigns to produce dynamic, three-dimensional LUR models which considered horizontal and vertical variation in air pollution concentration and population movements. This included the use of monitoring reference sites designed to measure background concentration to strengthen the temporal model component. In the absence of reference sites, studies have used temporal variables describing meteorology and have incorporated satellite data including Aerosol Optical Density (AOD) for PM<sub>2.5</sub> and NO<sub>2</sub> column data (Anand and Monks, 2017; Shi et al., 2018). Whilst satellite data has been shown to improve LUR model performance, its use is restricted by cloud coverage which reduces its suitability for use in the development of spatiotemporal models for regions commonly covered by cloud. In Europe, Chemical Transport Models (CTMs) have been used in LUR models and shown to improve model performance (De Hoogh et al., 2016).

Since the relationships of temporal variables and pollutant concentrations are often complex and non-linear, more sophisticated modelling techniques are often required. Generalised additive models (GAMs), for example, allow handling of non-linear relationships using smooth terms.

Dimakopoulou et al. (2018), used smooth terms to model the relationship between spatial and temporal variables with air pollution concentrations (Xu et al., 2019). The additive nature of GAMs means that the effect of each variable on the predicted outcome is independent of other variables, which allows for interpretation of the impact of each variable on the explained variability of measured concentrations.

The Complex Lipids in Mothers and Babies (CLIMB) study recruited a total of 1500 women in from two hospitals in Chongqing, China. Complex lipids are important constituents of the central nervous system, and studies have shown that supplementation during pregnancy may improve offspring cognitive outcomes (Vickers et al., 2009; Gurnida et al., 2012). The primary aim of the CLIMB study was to study the effects of supplementation of complex lipids in pregnancy on maternal ganglioside status and offspring cognitive outcomes. The data collected also presents an opportunity to study the relationship between air pollution exposure and a range of pregnancy outcomes, including pregnancy complications and fetal biometry, and offspring outcomes such as infant cognitive development, growth and general health in a population of pregnant women (Huang et al., 2017; Norris et al., 2019). To enable such research to be conducted, this study aimed to develop and validate granular spatiotemporal LUR models for PM<sub>2.5</sub> and NO<sub>2</sub> in Chongqing, China.

## 2. Methods

### 2.1. Study area

The study area focussed on the urban centre of the Chinese municipality of Chongqing (Fig. 1). With a population of approximately 6.52 million and a land area of 5472 km<sup>2</sup>, the study area has a high population density of approximately 1191 people/km<sup>2</sup> (Chongqing Municipal Bureau of Statistics, 2015). The city is characterised by high-rise buildings within a valley where the Yangtze and Jialing rivers converge,

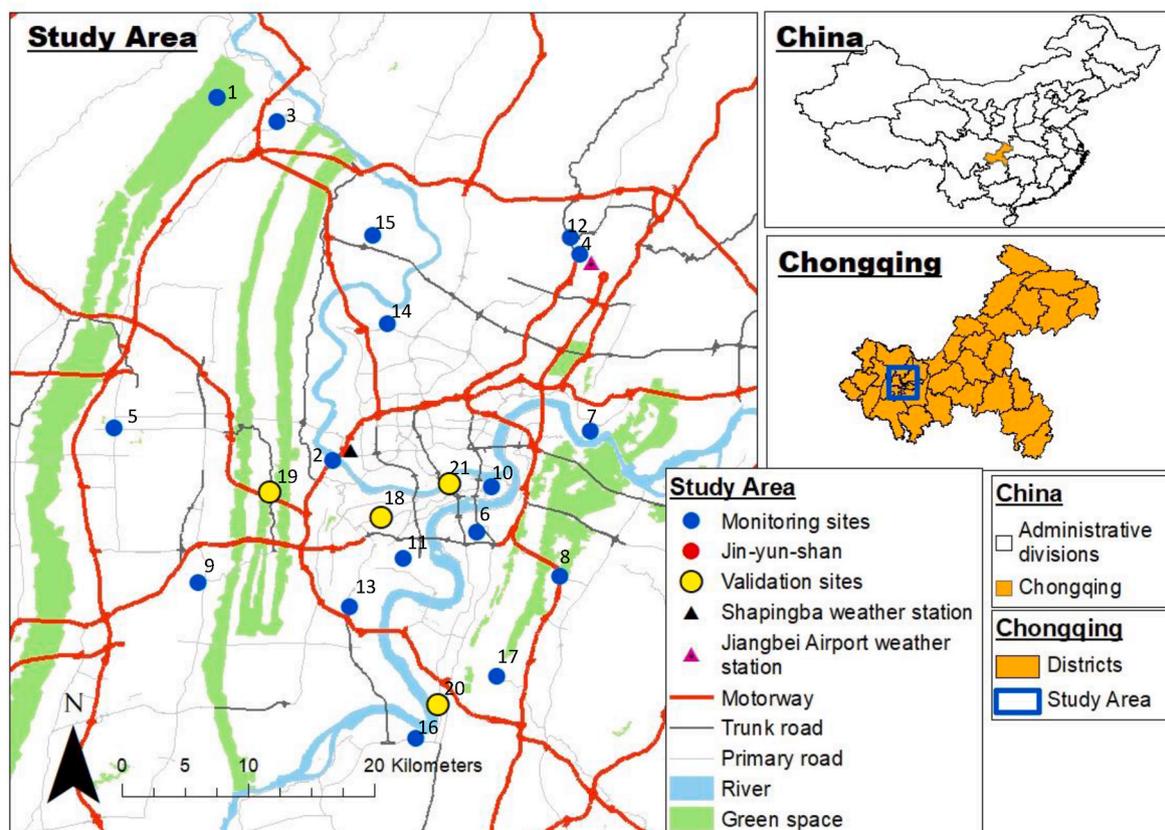


Fig. 1. Study area and location of monitoring sites (OpenStreetMap contributors, 2015; <https://data.nextgis.com/en/region/CN-50/>).

and the surrounding rural area is bounded to the west by mountains. Chongqing is considered one of the four ‘furnace cities’ of China due to its long and hot summers (Xinhua, 2012). In contrast, winters tend to be mild with low wind speeds and temperature inversions (Liao et al., 2018). Rain falls all year round, although summer is considered the rainy season (Wang et al., 2020). Chongqing experiences one of the lowest levels of sunshine in China, with only 1178.7 sunshine hours in 2018 (Wong, 2020).

## 2.2. Air pollution measurement data

Hourly PM<sub>2.5</sub> and NO<sub>2</sub> measurements taken from January 2, 2015 (data was not available for the January 1, 2015) to December 31, 2017 were obtained from the Chongqing Ecological Protection Bureau (2020). Monitoring sites were given a site ID number and classified as traffic sites if they were <100 m from a major road (motorway, trunk road, primary road), and background sites if they were >100 m away from a major road (Table S1, supporting information). In 2015, measurements were taken at a total of 17 sites, of which 6 are traffic sites and 11 are background sites, and 14 are in urban areas and 2 in suburban areas. Site 1 is in a rural forested area at relatively high altitude and is not representative of residential locations, therefore it was excluded from model development. In October and November 2016, Sites 2, 11 and 17 were discontinued and activity at the urban traffic sites 18 and 20, and suburban background site 19 started. On September 30, 2017, activity at Site 10 ceased and activity at urban background site 21 started. Values reported as PM<sub>2.5</sub> and NO<sub>2</sub> concentrations of 0 were considered as missing data.

## 2.3. Model development

### 2.3.1. Model formulation

The spatiotemporal models took the following form:

$$Y_{ij} = \alpha + \sum (\beta X_i) + \sum (f(Z_j)) + f(Long_i) + f(Lat_i) + \epsilon_{ij}$$

where  $Y_{ij}$  represents the predicted daily average pollutant concentrations at location  $i$  and on day  $j$ .  $\alpha + \sum (\beta X_i)$  represents the spatial component of the models, where  $\alpha$  is the intercept and  $\beta$  is the coefficient of each GIS predictor variable  $X$ .  $\sum (f(Z_j))$  represents the temporal term, where  $f(Z_j)$  is the smooth function of temporal variables  $Z$ .  $f(Long_i)$  and  $f(Lat_i)$  are the smooth terms of longitude and latitude, respectively, and  $\epsilon$  is the random error term. The approach therefore combines linear regression models for the spatial terms and generalised additive models (GAM) for the temporal terms and location.

### 2.3.2. Spatial predictor variables

Spatial variables were calculated for each site using the monitoring site coordinates and GIS data in ArcMap 10.8 software with a map projection of WGS 72BE South China Sea Lambert Conformal Conic. Variables were generated to reflect air pollution sources and sinks. The following groups of variables were generated: road network, land use, topography, vegetation, and population density. Road network variables included distance to nearest road and lengths of roads within circular buffers of radii 25 m, 50 m, 100 m, 300 m, 500 m and 1000 m to reflect local influences of nearby traffic and the influence of road density on the urban background concentration. The different road types used are summarised in Table S2. Land use and vegetation variables were derived using circular buffers of radii 300 m, 500 m, 1000 m and 5000 m. The vegetation variables were based on the Normalised Difference Vegetation Index (NDVI) developed from Moderate Resolution Imaging Spectroradiometer (MODIS) images in which cloud coverage did not negatively impact the data quality over the study area. Images taken on two days (July 12, 2015 and August 29, 2015) met these criteria and were merged to produce average NDVI. Population density at the point locations of monitoring sites was extracted from a 1 km grid. The

average population density within circular buffers was not used since the population density data had a relatively low spatial resolution of 1 km. Site elevation was extracted from a digital elevation model and distance to centre (using site 10 as the centre; see Fig. 1) was calculated for each site. A description of the potential spatial variables can be found in Table S3. The GIS data used were obtained from the following sources:

1. Road network data was from OpenStreetMap (OpenStreetMap contributors, 2015; <https://data.nextgis.com/en/region/CN-50/>).
2. Land use variables were derived from layers with a 100 m resolution in which the values of each pixel represented the fraction of each land use type within the pixel area. Data was provided by the Copernicus Global Land Service (Buchhorn et al., 2019).
3. Vegetation variables were based on the NDVI derived from images taken in 2015 from the MODIS MOD13Q1 v006 dataset which has a temporal resolution of 16 days and spatial resolution of 250 m (Didan, 2015).
4. A 1 km × 1 km population density grid was downloaded from the Chinese Academy of Sciences website (Xu, 2017).
5. Site elevation was extracted from the Global Digital Surface Model, which had a resolution of 30 m and was developed using data from the Advanced Land Observing Satellite (Tadono et al., 2016).

### 2.3.3. Spatial model component

The spatial models took the form:

$$Y_i = \alpha + \sum \beta X + \epsilon$$

where  $Y$  is the measured annual air pollution concentration at location  $i$ ,  $\alpha$  is the intercept,  $\beta$  is the coefficient to predictor variables  $X$  and  $\epsilon$  is the random error term.

The spatial component of the models was developed using a stepwise multiple linear regression approach which related the spatial variables to the daily average air pollutant concentration measurements taken at sites 2 to 17 in 2015. Measurements taken in 2016 were not used due to the closure of three monitoring sites. Variable selection involved use of a similar algorithm to those employed by previous studies (Abernethy et al., 2013; Habermann et al., 2015). *A priori* assumptions regarding the direction of correlation between each variable and annual average air pollutant concentrations were made based on prior knowledge of air pollution sources and sinks, and variables filtered as follows:

1. Variables for which the correlation did not match the *a priori* assumption were excluded.
2. Remaining variables were ranked in each sub-group by the size of the correlation coefficient.
3. Within each sub-group, variables which were strongly correlated ( $r > 0.6$ ) with the highest ranked variable were excluded.

Developed models ensured that the direction of the effect of each variable was consistent with the *a priori* assumption and that variables were statistically significant ( $p < 0.05$  for entry and  $p < 0.1$  in the final model) and had a variance inflation factor of less than 3. Models were also checked for outliers using Cook’s Distance.

### 2.3.4. Temporal predictor variables

Meteorological variables were used to account for the influence of weather on the change in air pollution concentration over time (i.e. day-to-day, season). Measurement data from the Shapingba weather station (Fig. 1) was downloaded from the National Centers for Environmental Information website (National Centers for Environmental Information, 2020), and data from the Jiangbei Airport weather station was downloaded from the Reliable Prognosis 5 website (Raspisaniye Pogodi Ltd, 2020). Since the location of the Shapingba weather station was more central than the Jiangbei station, measurements from the Shapingba

station were used to generate the variables of daily average temperature, amount of rainfall in the past 24 and 48 h and a binary variable for rainfall events. On days where data from the Shapingba weather station was missing, data from the Jiangbei station were used. Measurements taken at the Jiangbei Airport station were used to generate the following daily average variables: relative humidity, horizontal visibility, wind direction and wind speed. The daily average wind direction was calculated using the Openair R package (Carslaw and Ropkins, 2012). The temporal variables generated are summarised in Table S4.

### 2.3.5. Temporal model component

The temporal component took the form:

$$Y_j = \sum (f(Z_j)) + \varepsilon_j$$

where  $Y$  is the predicted daily residuals on day  $j$ ,  $f(Z_j)$  are smooth functions of the temporal variables  $Z$  and  $\varepsilon$  is the random error term.

The temporal component of models was developed using the mgcv package in R (Wood, 2011). The temporal GAMs were fitted to the residuals from spatial component at each monitoring site on a daily basis, calculated by subtracting the predicted annual average concentration from the observed daily average concentrations measured in 2015 and 2016. Fig. S1-S5 presents descriptive statistics and the univariate relationships between temporal variables and daily average pollutant concentrations, which were used to identify terms to include in the GAMs. Identified variables were included in the temporal  $PM_{2.5}$  and  $NO_2$  GAMs if they were significant ( $p < 0.05$ ).

The optimal number of basis dimensions was determined through graphical analysis of GAMs to ensure that modelled relationships did not overfit the measurement data and key aspects of relationships were not missed. The smoothing parameter values were estimated using the Restricted Maximum Likelihood method (Wood, 2011).

### 2.3.6. Remaining spatial autocorrelation

To account for the remaining spatial autocorrelation, the smooth terms of longitude and latitude were fitted to spatiotemporal residuals which were calculated by subtracting the sum of the spatial temporal predictions from the measured daily average concentrations in 2015 and 2016. The terms took the form:

$$S_i = f(Long_i) + f(Lat_i)$$

where  $S_i$  is the spatiotemporal residual at location  $i$ , and  $f(Long_i)$  and  $f(Lat_i)$  represent smooth terms of longitude and latitude, respectively. The term was included in the spatiotemporal models if it was statistically significant ( $p < 0.05$ ).

## 2.4. Model performance and validation

Spatial predictions were assessed through comparison of the measured and predicted annual average pollutant concentration in 2015 and via leave-one-out-cross-validation (LOOCV). The LOOCV involved the removal of the annual average concentration at each site in turn and refitting the model to the annual average concentrations at the remaining sites whilst maintaining the same variables.

Measured daily, weekly and monthly average pollutant concentrations from training sites in 2017, including four newly opened sites (Sites 18–21), were used for hold-out validation (HOV). The performance of spatiotemporal models was assessed through analysis of measured against predicted pollutant concentrations to produce four groups of performance statistics: COR- $R^2$  (square of Pearson's correlation coefficient), MSE- $R^2$  (mean-square-error-based- $R^2$ ; i.e. 1 - (mean square error/variance of observations)), RMSE (root-mean-square-error), and NRMSE (normalised root mean square error; i.e. RMSE/interquartile range (IQR) of the observations). In addition to COR- $R^2$ , some studies have used MSE- $R^2$  as a composite measure of correlation and bias to provide a more stringent test of model prediction performance

(Gulliver et al., 2016; Knibbs et al., 2018; Wang et al., 2012).

A summary of the data used in model development and validation is provided in Table 1.

## 2.5. Exposure assessment of CLIMB study participants

The study utilised data collected on pregnant women enrolled in the CLIMB study, a three armed randomized controlled trial of a complex milk lipid supplement during pregnancy that was first established in Chongqing, China from September 2015 (Huang et al., 2017; Norris et al., 2019). Women were recruited in their first trimester of pregnancy from the First Affiliated Hospital of Chongqing Medical University and Chongqing Health Centre for Women and Children (CHCWC) in China. Recruitment was completed in June 2017. Eligible gravidas were aged 20–40 years and had a singleton pregnancy. Women with a history of premature delivery before 32 weeks of gestation, known milk allergy or aversion, or lactose intolerance were excluded. Women who withdrew from the study, whose pregnancies were terminated, who miscarried, or were lost to follow up ( $n = 40$ ), were excluded from the analysis.

The developed spatiotemporal models were used to estimate the  $PM_{2.5}$  and  $NO_2$  exposures of 1183 of the 1500 participants recruited in the CLIMB study (Huang et al., 2017; Norris et al., 2019) for whom the detailed residential addresses during pregnancy were known. Using the R software (Wood, 2011), the average exposures in the 1st, 2nd and 3rd trimesters and throughout pregnancy were predicted, as well as during the 90 days prior to conception, since this has been reported to be a critical exposure period (Robledo et al., 2015).

## 3. Results

### 3.1. Measured concentrations

Fig. 2 presents the variability in the annual average  $NO_2$  and  $PM_{2.5}$  concentrations in 2015, the year used for development of the spatial component. During this period, the annual average  $NO_2$  and  $PM_{2.5}$  concentrations were  $44.9 \mu\text{g}/\text{m}^3$  (SD =  $8.4 \mu\text{g}/\text{m}^3$ ) and  $55.9 \mu\text{g}/\text{m}^3$  (SD =  $2.8 \mu\text{g}/\text{m}^3$ ), respectively. There was greater variation in the annual average  $NO_2$  concentration (range =  $30.6 \mu\text{g}/\text{m}^3$ ) than in that of  $PM_{2.5}$  concentration (range =  $11.1 \mu\text{g}/\text{m}^3$ ). Site 10, an urban centre background site, recorded the highest annual average  $NO_2$  ( $63.4 \mu\text{g}/\text{m}^3$ ) and  $PM_{2.5}$  concentrations ( $63.6 \mu\text{g}/\text{m}^3$ ). Aside from Site 1, which was considered a spatial outlier and was excluded from model development, Site 9, an urban background site (Airport site), reported the lowest annual average  $NO_2$  concentration ( $32.8 \mu\text{g}/\text{m}^3$ ) and Site 5, an urban traffic site, reported the lowest annual average  $PM_{2.5}$  concentration

**Table 1**

Summary of data used for model development and validation.

	Site ID <sup>a</sup>	Measurement time period <sup>b</sup>
Spatial component	2 to 17	January 2, 2015–December 31, 2015
Temporal component	3 to 10 and 12 to 16	January 2, 2015–December 31, 2016
	2	January 2, 2015–October 22, 2016
	11	January 2, 2015 – November 5, 2016
	17	January 2, 2015–November 13, 2016
Hold-out validation	3 to 9 and 12 to 16	January 1, 2017–December 31, 2017
	10	January 1, 2017–September 30, 2017
	18 to 20	November 21, 2016–December 31, 2017
	21	September 30, 2017–December 31, 2017

<sup>a</sup> The ID of sites at which measurements used in the corresponding stage of model development and validation were taken.

<sup>b</sup> The time period over which the measurements in the corresponding stage of model development and validation were taken.

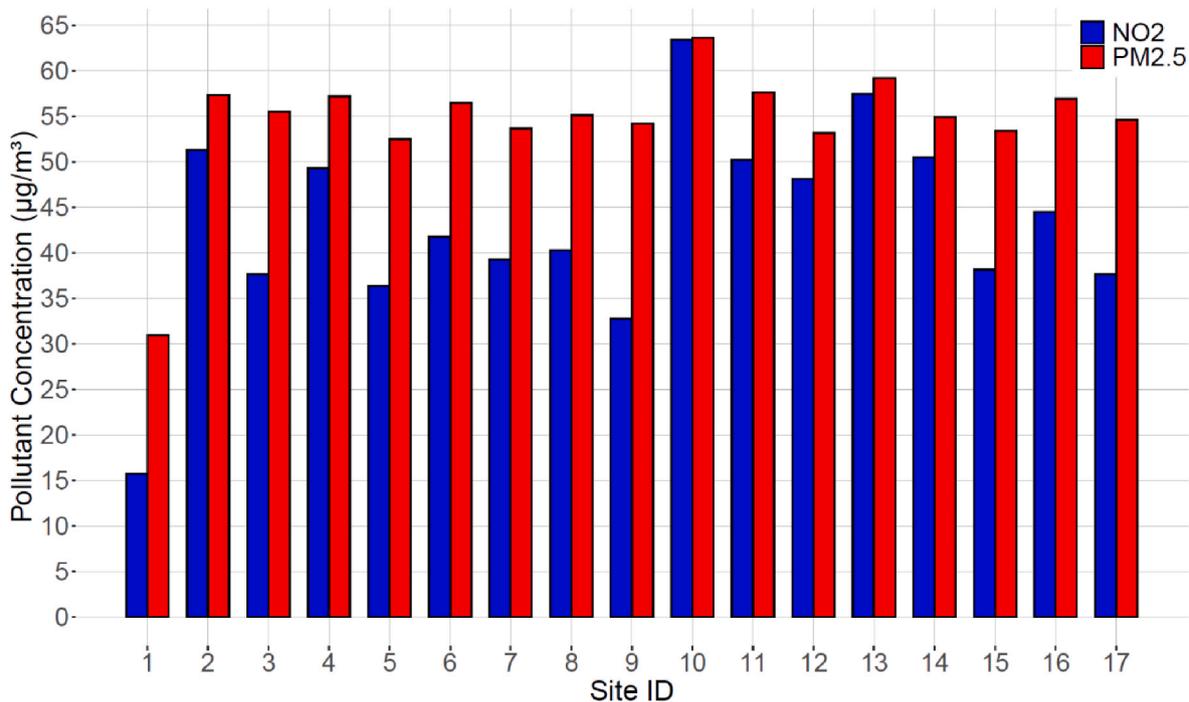


Fig. 2. Variation in measured annual averages of NO<sub>2</sub> and PM<sub>2.5</sub> concentration by site in 2015.

(52.5 µg/m<sup>3</sup>). Fig. S6 presents the variability in the annual average NO<sub>2</sub> and PM<sub>2.5</sub> concentrations in 2016 and 2017 which both include site location changes, hence the spatial model was developed using sites only from 2015.

The temporal model was developed using daily average measurements from 2015 to 2016. Daily average measurements in 2015 and 2016 are presented graphically in Fig. S2 and S3. Average monthly concentrations are summarised in Table S5. Across the winter months of January to March and October to December in both years, PM<sub>2.5</sub> and NO<sub>2</sub> concentrations were generally higher and showed greater variation (in winter 2015, average PM<sub>2.5</sub> = 70.5 µg/m<sup>3</sup> (SD = 42.9), NO<sub>2</sub> = 47.8 µg/m<sup>3</sup> (SD = 14.1 µg/m<sup>3</sup>; in winter 2016, average PM<sub>2.5</sub> = 61.3 µg/m<sup>3</sup> (SD = 30.7), NO<sub>2</sub> = 50.6 µg/m<sup>3</sup> (SD = 12.7)) compared to summer months of April to September. In summer 2015, average PM<sub>2.5</sub> = 41.7 µg/m<sup>3</sup> (SD = 15.9 µg/m<sup>3</sup>), NO<sub>2</sub> = 42.3 µg/m<sup>3</sup> (SD = 42.2 µg/m<sup>3</sup>); in summer 2016, average PM<sub>2.5</sub> = 46.8 µg/m<sup>3</sup> (SD = 20.0 µg/m<sup>3</sup>), NO<sub>2</sub> = 42.1 µg/m<sup>3</sup> (SD = 11.0 µg/m<sup>3</sup>). Air pollutant concentration did not vary

significantly by day of the week (Fig. S1). In 2015, 2016 and 2017, the percentages of missing PM<sub>2.5</sub> measurements were 1.9%, 2.8% and 1.4%, and those of NO<sub>2</sub> measurements were 2.5%, 2.9% and 1.4%, respectively.

### 3.2. Model variables

Variables included in the spatiotemporal models are summarised in Table 2. In the NO<sub>2</sub> and PM<sub>2.5</sub> spatial models, the length of Highways within a 500 m circular buffer (Highway\_500) variable was included and was the most important variable in both models (partial R<sup>2</sup> = 0.54 in the PM<sub>2.5</sub> model, partial R<sup>2</sup> = 0.31 in the NO<sub>2</sub> model). In addition, the average NDVI within a 5000 m circular buffer (NDVI\_5000) was included in the NO<sub>2</sub> model, and the fraction of land within a 5000 m circular buffer which was rural (Rural\_5000) was included in the PM<sub>2.5</sub> model. For the PM<sub>2.5</sub> model, the partial R<sup>2</sup> values were as follows: 0.54 for Highway\_500, 0.33 for Rural\_5000. For the NO<sub>2</sub> model, the partial R<sup>2</sup>

Table 2  
Summary of the spatial and temporal components of the PM<sub>2.5</sub> and NO<sub>2</sub> models.

Linear terms	PM <sub>2.5</sub>						NO <sub>2</sub>					
	B	SE B	β	p	Partial R <sup>2</sup>	ΔR <sup>2</sup>	B	SE B	β	p	Partial R <sup>2</sup>	ΔR <sup>2</sup>
Spatial intercept	56.0	1.6	–	<0.01	–	–	59.5	11.9	–	<0.01	–	–
Temporal intercept	3.12	1.07	–	<0.01	–	–	–	–	–	–	–	–
Rural 5000	–0.049	0.020	–0.48	0.02	0.33	–	–	–	–	–	–	–
HW 500	7.5e-4	1.9e-4	0.61	<0.01	0.54	–	1.8e-3	7.7e-4	0.49	0.03	0.31	–
NDVI 5000	–	–	–	–	–	–	–3.8e-3	1.8e-3	–0.43	0.05	0.26	–
Rain in 48 h	–6.66	1.50	–	<0.01	–	0.01	–	–	–	–	–	–
Smooth terms	k	edf	p	ΔR <sup>2</sup>	k	edf	p	ΔR <sup>2</sup>				
Month	3	1.98	<0.01	0.04	5	3.67	<0.01	0.03				
Temperature	5	3.79	<0.01	0.01	9	5.00	<0.01	0.05				
Horizontal visibility	9	5.72	<0.01	0.31	9	1.00	<0.01	0.07				
Relative humidity	9	5.53	<0.01	0.11	9	3.51	<0.01	0.13				
Wind speed	–	–	–	–	9	2.03	<0.01	0.07				

B, unstandardized coefficient; SE B, standard error of coefficients (B); β, standardized coefficient; p, probability value for significance; Partial R<sup>2</sup>, coefficient of partial determination; ΔR<sup>2</sup>, change in R<sup>2</sup> when the variable was removed; Rural 5000, fractional cover of rural land within a 5000 m circular buffer; HW 500, length of Highways within a 500 m circular buffer; NDVI 5000, average Normalised Difference Vegetation Index within a 5000 m circular buffer; k, number of basis dimensions; edf, effective degrees of freedom.

values were as follows: 0.31 for Highway\_500, 0.26 for NDVI\_5000. The multiple linear regression assumptions were assessed graphically (Fig. S7 and S8). Whilst the NO<sub>2</sub> model met all assumptions tested for, the PM<sub>2.5</sub> model failed to meet the assumption of normality at extreme low and high concentrations, and the measured annual average

concentration at Site 10 acted as an influential observation (Cook's D = 1.6). Modelled annual average PM<sub>2.5</sub> and NO<sub>2</sub> concentration surfaces for the study area are presented in Fig. 3.

Smooth terms for month, temperature, horizontal visibility and relative humidity variables were selected for inclusion in both PM<sub>2.5</sub> and

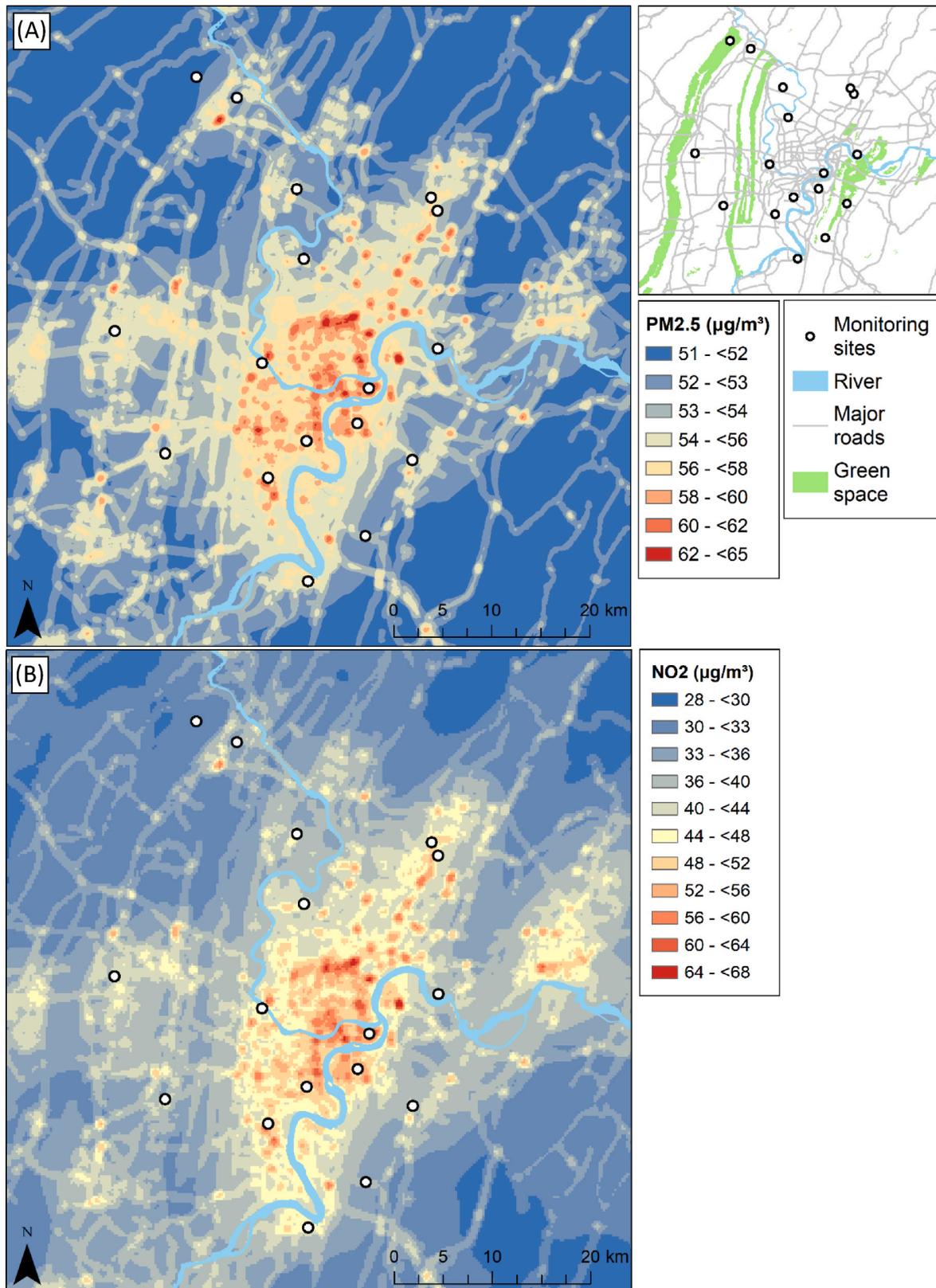


Fig. 3. Modelled annual average PM<sub>2.5</sub> (A) and NO<sub>2</sub> (B) concentration in 2015.

NO<sub>2</sub> temporal GAMs. In addition, a linear term of the binary variable describing the presence or absence of rainfall within 48 h was included in the PM<sub>2.5</sub> GAM and a smooth term of the wind speed variable was included in the NO<sub>2</sub> GAM. In the PM<sub>2.5</sub> GAM, the number of basis dimensions (*k*) specified for temperature and month smooth terms were 5 and 3, respectively. In the NO<sub>2</sub> GAM, *k* was 5 for the month smooth term. For other included variables, the default *k* was used (*k* = 9). The most important variable in the PM<sub>2.5</sub> GAM was visibility (*R*<sup>2</sup> change = 0.31) with low visibility related to increased PM<sub>2.5</sub> concentrations. The most important variable in the NO<sub>2</sub> GAM was humidity (*R*<sup>2</sup> change = 0.13), with high humidity related to decreased NO<sub>2</sub> concentrations. In both GAMs, pollutant concentrations were highest in winter and lowest in summer. The partial effect plots for the PM<sub>2.5</sub> and NO<sub>2</sub> GAMs are presented in Fig. S9 and S10. The GAM assumptions were tested graphically (Fig. S11 and S12). Both the PM<sub>2.5</sub> and NO<sub>2</sub> GAMs met the assumption of homogeneity, however, at extreme low and high concentrations the assumption of normality was not met. The longitude and latitude smooth terms, which accounted for remaining spatial autocorrelation, were only included in the NO<sub>2</sub> spatiotemporal model.

### 3.3. Model evaluation

For the PM<sub>2.5</sub> spatial component, model development yielded 0.78 for COR-R<sup>2</sup>, 0.79 for MSE-R<sup>2</sup>, 1.2 µg/m<sup>3</sup> for RMSE and 0.39 for NRMSE. For the NO<sub>2</sub> spatial component, model development yielded 0.71 for COR-R<sup>2</sup>, 0.73 for MSE-R<sup>2</sup>, 4.4 µg/m<sup>3</sup> for RMSE and 0.36 for NRMSE. For the PM<sub>2.5</sub> spatial component, the LOOCV values were 0.60 for COR-R<sup>2</sup>, 0.62 for MSE-R<sup>2</sup>, 1.7 µg/m<sup>3</sup> for RMSE and 0.54 for NRMSE. For the NO<sub>2</sub> spatial component, the LOOCV values were 0.58 for COR-R<sup>2</sup>, 0.60 for MSE-R<sup>2</sup>, 5.3 µg/m<sup>3</sup> for RMSE and 0.44 for NRMSE. Performance and validation statistics are summarised in Table S6.

Table 3 shows summary statistics combining all sites for daily and monthly COR-R<sup>2</sup>, MSE-R<sup>2</sup>, RMSE and NRMSE of the PM<sub>2.5</sub> and NO<sub>2</sub> spatiotemporal LUR models. The values for individual sites are presented in Table S7.

For spatiotemporal model development (i.e. using measurements from 2015 to 2016), the average COR-R<sup>2</sup> of the PM<sub>2.5</sub> was 0.72 and for NO<sub>2</sub> was 0.39. HOV yielded similar results, whereby the PM<sub>2.5</sub> model had good performance (HOV daily COR-R<sup>2</sup> = 0.75; monthly COR-R<sup>2</sup> = 0.87) and the NO<sub>2</sub> model had moderate performance (HOV daily COR-R<sup>2</sup> = 0.44; monthly COR-R<sup>2</sup> = 0.65). The average HOV MSE-R<sup>2</sup> of the PM<sub>2.5</sub> model (HOV daily MSE-R<sup>2</sup> = 0.69; monthly MSE-R<sup>2</sup> = 0.76) was substantially greater than that of the NO<sub>2</sub> model (HOV daily MSE-R<sup>2</sup> = 0.24; monthly MSE-R<sup>2</sup> = -0.02) and the NO<sub>2</sub> spatiotemporal model predictions were subject to greater bias than those of the PM<sub>2.5</sub> spatiotemporal model.

**Table 3**

Performance of spatiotemporal land use regression models.

	COR-R <sup>2</sup>		MSE-R <sup>2</sup>		RMSE (µg/m <sup>3</sup> )		NRMSE	
	Daily	Monthly	Daily	Monthly	Daily	Monthly	Daily	Monthly
PM <sub>2.5</sub>								
2015–2016	0.72 (0.67–0.77)	0.84 (0.77–0.89)	0.71 (0.66–0.76)	0.83 (0.78–0.88)	17.5 (15.3–20.1)	8.7 (7.2–10.5)	0.32 (0.28–0.37)	0.16 (0.13–0.19)
HOV	0.75 (0.68–0.80)	0.87 (0.74–0.97)	0.69 (0.53–0.75)	0.76 (0.47–0.91)	17.8 (16.2–20.9)	10.7 (7.3–14.2)	0.54 (0.48–0.68)	0.36 (0.25–0.55)
NO <sub>2</sub>								
2015–2016	0.39 (0.24–0.50)	0.61 (0.29–0.86)	0.31 (0.00–0.49)	0.33 (–0.45–0.78)	12.8 (9.2–16.3)	5.9 (3.0–11.1)	0.29 (0.23–0.42)	0.13 (0.08–0.26)
HOV	0.44 (0.30–0.69)	0.65 (0.35–0.88)	0.24 (–0.17–0.59)	–0.02 (–1.39–0.66)	13.4 (9.6–17.7)	8.4 (4.1–13.2)	0.62 (0.49–0.76)	0.68 (0.35–1.12)

COR-R<sup>2</sup>, MSE-R<sup>2</sup>, RMSE, and NRMSE are presented as the mean, with minimum and maximum in parentheses, of the COR-R<sup>2</sup>, MSE-R<sup>2</sup>, RMSE, and NRMSE values achieved across sites (Table S7 and S8). Abbreviations: COR-R<sup>2</sup>, Pearson's correlation coefficient, squared; MSE-R<sup>2</sup>, mean-square-error-based-R<sup>2</sup>; RMSE, root mean square error; NRMSE, normalised root mean square error (normalised by the inter-quartile range (IQR) of measurements); HOV, hold-out validation.

### 3.4. Exposure assessment of CLIMB study participants

Fig. 4 shows the variation in the estimated exposure to PM<sub>2.5</sub> and NO<sub>2</sub> during the 90 days prior to pregnancy, 1st, 2nd and 3rd trimesters and during the whole of pregnancy. Table S9 presents the summary statistics. The estimated PM<sub>2.5</sub> and NO<sub>2</sub> exposures of CLIMB study participants over the whole pregnancy were 57.4 µg/m<sup>3</sup> (SD = 4.0 µg/m<sup>3</sup>) and 50.5 µg/m<sup>3</sup> (SD = 5.1 µg/m<sup>3</sup>), respectively. The estimated PM<sub>2.5</sub> exposures during the 90 days prior to conception (mean = 52.9 µg/m<sup>3</sup>; SD = 11.0 µg/m<sup>3</sup>), 1st (mean = 52.0 µg/m<sup>3</sup>; SD = 11.0 µg/m<sup>3</sup>), 2nd (mean = 58.6 µg/m<sup>3</sup>; SD = 12.2 µg/m<sup>3</sup>) and 3rd (mean = 61.8 µg/m<sup>3</sup>; SD = 16.0 µg/m<sup>3</sup>) trimesters showed greater variation than the corresponding NO<sub>2</sub> exposures during the 90 days prior to conception (mean = 49.6 µg/m<sup>3</sup>; SD = 6.3 µg/m<sup>3</sup>), 1st (mean = 48.8 µg/m<sup>3</sup>; SD = 6.3 µg/m<sup>3</sup>), 2nd (mean = 51.0 µg/m<sup>3</sup>; SD = 6.2 µg/m<sup>3</sup>) and 3rd (51.8 µg/m<sup>3</sup>; SD = 6.8 µg/m<sup>3</sup>) trimesters.

## 4. Discussion

Spatiotemporal LUR models for estimating daily and monthly average PM<sub>2.5</sub> and NO<sub>2</sub> concentration estimates were developed for Chongqing, China. The PM<sub>2.5</sub> spatiotemporal model had good performance when providing concentration estimates in absolute terms. Whilst the ability of the NO<sub>2</sub> spatiotemporal model to provide concentration estimates in absolute terms was substantially weaker than for PM<sub>2.5</sub>, the ability of the model to provide a relative ranking for NO<sub>2</sub> was moderate.

The developed spatiotemporal LUR models were used to estimate the PM<sub>2.5</sub> and NO<sub>2</sub> exposure during time periods before and during the pregnancies of 1183 women who lived in Chongqing and were recruited as part of the CLIMB study (Huang et al., 2017; Norris et al., 2019). Exposure estimates highlighted that models could capture contrasts in space and time during different pregnancy exposure periods, although greater variation in average PM<sub>2.5</sub> exposure compared to NO<sub>2</sub> was observed.

### 4.1. Performance of the spatiotemporal land use regression models

From measurements taken from the network of fixed-site monitors, there was greater spatial variation in concentrations of NO<sub>2</sub> than PM<sub>2.5</sub> and, conversely, greater temporal variation in concentrations of PM<sub>2.5</sub> than NO<sub>2</sub>. Since the spatial component of the models was based on annual average concentrations from 16 measurement sites and the temporal component was developed from data covering 730 days (the measured daily average concentrations from 2015 to 2016), the models had a comparatively weak spatial basis and strong temporal basis. Hence, we yielded more accurate predictions of PM<sub>2.5</sub> concentrations than NO<sub>2</sub> concentrations overall. NO<sub>2</sub> models performed well in HOV in

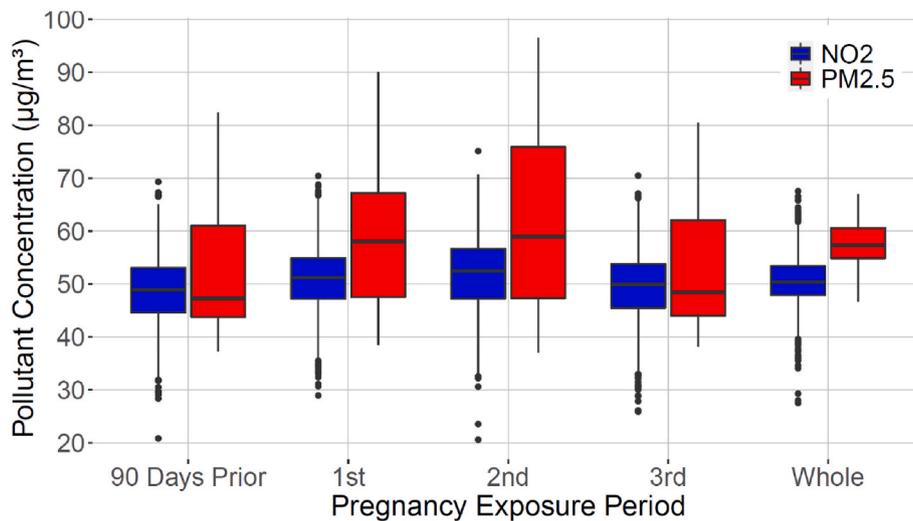


Fig. 4. Exposure assessment of CLIMB study participants.

terms of correlation ( $COR-R^2$ ) and poor-to-good depending on the site and poorly overall in terms of  $MSE-R^2$ . It is not completely clear why  $NO_2$  model performance was stronger at some sites compared to others, but there was a tendency for  $MSE-R^2$  to be lower at sites close to highways which suggests weaknesses in the variables accounting for fluctuations in traffic. The overall performance suggests that using the  $NO_2$  spatiotemporal model to provide relative rankings of concentration would be more appropriate than using the model to provide concentration estimates in absolute terms. Models for  $PM_{2.5}$  performed well overall and may be applied to predict absolute values of exposures.

We used a two-stage approach to model development: 1) the spatial variables were selected using a multiple linear regression model and 2) the residuals from the spatial model were included along with meteorological variables and month of year in a spatiotemporal GAM. One option was to include both the spatial and temporal variables in the GAM, which would have allowed the two groups of variables to interact. However, this approach was seen in experimentation to suppress the ability of the models to capture spatial contrasts in concentrations for both the  $NO_2$  and  $PM_{2.5}$  models. Therefore, the two-stage approach which was adopted in this paper was favoured.

#### 4.2. Variables included in the spatiotemporal land use regression models

The models incorporated spatial variables describing the road network, land use and vegetation. Land use and vegetation variables represented the influence of areas of greenspace in Chongqing where the urban background concentration was lower due to the absence of air pollution sources. The length of highways (motorways, trunk roads, primary roads, secondary roads and tertiary roads) within a 500 m circular buffer, which was included in both  $PM_{2.5}$  and  $NO_2$  models, accounted for the influence of traffic on air pollution concentrations. In areas of high road density there were likely more high-rise buildings and narrower streets. Therefore, the highways variable may have also acted as a proxy for the effect of street canyons where air pollution dispersion from traffic is reduced resulting in higher pollutant concentrations at the road-side (Park et al., 2004).

The temporal GAMs incorporated meteorological variables and a variable to describe month which modelled the seasonal change in pollutant concentration. In both the  $PM_{2.5}$  and  $NO_2$  temporal GAMs, inclusion of horizontal visibility greatly increased GAM performance and was likely to have accounted for the level of smog. In the  $NO_2$  GAM, wind speed was included to account for reduced  $NO_2$  concentrations associated with higher wind speed (Zhang et al., 2015). In the  $PM_{2.5}$  GAM, the binary rainfall variable accounted for the wet deposition of

particulate matter which reduces concentration (Guo et al., 2016). An explanation for the observed relationships between pollutant concentrations with daily average relative humidity and temperature in the GAMs was unclear. Both temperature and humidity demonstrated seasonal variation (whereby temperature tended to be lower in winter and higher in summer, and humidity tended to be higher in winter and lower in summer). Therefore, interpretation of the relationships between pollutant concentration with daily average temperature and relative humidity was complicated by concurvity (the nonparametric analogue of multicollinearity; Ramsey et al., 2003) between the daily average relative humidity and temperature variables with the month variable. The same meteorological variables included in the spatiotemporal models have also been included in other  $PM_{2.5}$  and  $NO_2$  spatiotemporal models (Shi et al., 2018; Zhang et al., 2020), which highlights their relevance in different settings. Overall, weather conditions had a greater influence on the variability in  $PM_{2.5}$  concentrations than the variability in  $NO_2$  concentrations.

Anand and Monks (2017) and Shi et al. (2018) incorporated satellite derived data including column density (OMI) for  $NO_2$  and AOD for  $PM_{2.5}$  and found that these variables improved LUR model performance. Chongqing has the second lowest number of sunshine hours for cities in China (Wong, 2020) and subsequently satellite derived data was missing on many days due to cloud cover. Furthermore, we could not establish a daily dataset for  $NO_2$  from OMI. CTMs have also been shown to improve LUR model performance but at the time of this study there were no suitable CTMs for Chongqing. Limitations with these data sources meant that only meteorological variables were incorporated into the temporal component of the LUR models.

#### 4.3. Comparison with other land use regression models developed for regions in China

Wu et al. (2015) developed a spatial  $PM_{2.5}$  LUR model for Chongqing with similar variables to represent the main  $PM_{2.5}$  sources and sinks, but with different buffer sizes (primary road length within a 1000 m buffer, cropland within a 500 m buffer), and also elevation. Wu et al. (2015) reported higher model  $R^2$  (0.84) than the spatial component of the  $PM_{2.5}$  spatiotemporal model developed in the present study. However, their inclusion of measurements taken at Site 1, excluded from model development in the present study, may have been an outlier and resulted in inflation of model performance. This conjecture is supported by Wu et al. (2015) including an elevation variable which likely reflected the influence of Site 1 (altitude of 724 m) as it is 296 m higher in altitude than the next highest site and there is a comparatively low level of

variability in elevation between the other sites. Direct comparison of the performance of the spatial component of our model and Wu et al. (2015) is not possible as they are based on measured concentrations from different years.

The spatiotemporal models developed for Wuhan, and subsequently used in birth cohort studies, were based on measurements taken at 10 to 20 monitoring sites (Kang et al., 2020; Liao et al., 2019; Liu et al., 2019; Song et al., 2019). Five spatial variables were incorporated into a PM<sub>2.5</sub> spatiotemporal model (Kang et al., 2020; Liao et al., 2019; Liu et al., 2019) and six spatial variables were incorporated into the NO<sub>2</sub> spatiotemporal model (Song et al., 2019). Models developed in the current study included only two spatial variables based on prior rules for variable selection (see section 2.3.3). We have provided a parsimonious model given the level of support (i.e. relatively low number of monitoring sites). There may be other sources of PM<sub>2.5</sub> and NO<sub>2</sub>, such as discrete areas of industry, that we were unable to represent due to limitations with the data available to produce predictor variables. Nonetheless, were able to differentiate exposures for the study population in terms of proximity to sources using major roads and sinks using rural areas and vegetation.

Although the Wuhan PM<sub>2.5</sub> spatiotemporal model reported the same model R<sup>2</sup> as that achieved by the PM<sub>2.5</sub> model developed in the present study (average daily R<sup>2</sup> = 0.72), lack of model parsimony may have increased the risk of the Wuhan models overfitting the data which would have inflated the model R<sup>2</sup> value (Gillespie et al., 2016; Hawkins, 2004). Since the risk of overfitting increases in models based on measurements taken at a relatively low number of sites (Gillespie et al., 2016), in the present study development of a parsimonious model was considered preferable.

Spatiotemporal LUR models developed for regions in China using measurements taken at a limited number of sites typically used cross-validation techniques to validate models. Basagaña et al. (2012) found that model R<sup>2</sup> and cross-validation R<sup>2</sup> were inflated in spatial LUR models developed using measurements taken at a limited number of monitoring sites and suggested that hold-out validation (HOV) provided a better indicator of model performance, but is not possible for studies with a low number of sites (i.e. ~20). We believe that there have been no studies which have investigated the effect of the number of monitoring sites on performance of spatiotemporal LUR models. In the present study, the HOV MSE-R<sup>2</sup> values of both PM<sub>2.5</sub> and NO<sub>2</sub> spatiotemporal models were similar to the model development MSE-R<sup>2</sup> values, with the exception of monthly models for NO<sub>2</sub> but we recognise the weakness of our study is the relatively lower number of measurement sites which may have limited our capacity to fully capture spatiotemporal contrasts in concentrations. In the absence of detailed emissions inventories to apply dispersion modelling, approaches that rely on statistical methods, such as LUR, would benefit from increasing the number of sites in routine monitoring networks or undertaking supplementary measurements at other locations. The latter however has implications for the affordability of these types of study.

Barratt et al. (2018) demonstrated that reference sites, which provide a good measure of background air pollutant concentration, can be used to strengthen the temporal component of models. In Chongqing, one option was to use Site 1 as a reference site to represent background concentration levels on a daily basis. The use of a reference site would however have prevented predictions being made on days where measurement data was missing and would have risked the model becoming non-functional for adaptation to years outside of the study period if that site closed.

#### 4.4. Strengths and limitations

This study had two main strengths. Firstly, the use of HOV provided a more robust test of performance of spatiotemporal models than the cross-validation techniques used in other studies which have developed spatiotemporal LUR models in China. Secondly, since the variables

included in the spatiotemporal LUR models are likely to be freely available for most urban areas, our models could be transferred and locally calibrated for use in other regions.

The study faced several limitations which provide direction for future research. In addition to the low number of monitoring sites mentioned above, we lacked data on traffic intensity of the road network and were therefore limited to creating variables based on road length or distance to road. Chongqing is characterised by high-rise buildings, yet we did not have data on individual building geometry with heights which limited our ability to statistically represent the effects of building density on dispersion (i.e. street canyons) and concentration variability. Previous studies have used potential predictor variables describing building height and street configuration such as aspect-ratio. Barratt et al. (2018) developed a three-dimensional LUR model for Hong-Kong and reported that the addition of street configuration and building height to reflect pollutant concentration in street canyons improved model performance. However, in their preferred LUR models, only the nitric oxide model included a building height variable and the other models incorporated variables similar to the potential predictor variables included in our study. Other studies have reported increases in model R<sup>2</sup> with inclusion of urban morphology variables between 2% and 13% (Eeftens et al., 2013; Shi et al., 2016; Su et al., 2008; Tang et al., 2013). Su et al. (2008) used measurements taken at 15 monitoring sites, which was similar to the number present in Chongqing, and they reported an increase in NO<sub>2</sub> model R<sup>2</sup> of 0.11 with inclusion of variables on building height, suggesting that inclusion of such variables in the present study would have improved model performance. Other studies used measurement data taken at a much greater number of monitoring sites than were available in Chongqing (≥100 for Barratt et al. (2018) and Eeftens et al. (2013) and >40 for Tang et al. (2013)) and Shi et al. (2016) used data provided by a mobile measurement campaign, which reduces their relevance to the present study. In the future, with increased LiDAR mapping coverage, it may be possible to obtain data regarding building heights in Chongqing for inclusion in LUR models.

Meteorological data was only available from two weather stations and it was unclear whether the weather experienced at these two stations would be experienced throughout the study area. Finally, some missing air pollution measurements may have negatively impacted LUR model development and performance. However, since the amount of missing data was small (<3%), the effect on model performance was likely to be minimal.

## 5. Conclusions

Air pollution exposure models are now available to study pregnancy outcomes in the CLIMB study in Chongqing. We recommend that PM<sub>2.5</sub> models are used for predicting absolute exposure whereas NO<sub>2</sub> models are used for relative ranking of exposures. Considering the data collected in the CLIMB study, the exposure estimates made could be used in future research studying the effects of maternal air pollution exposure on adverse pregnancy outcomes as well as infant cognitive development and health.

### Credit author statement

**Alexander Harper** - Conceptualization; Data curation; Formal analysis; Methodology; Validation; Roles/Writing - original draft; Writing - review & editing. **Philip N. Baker** - Conceptualization; Funding acquisition; Writing - review & editing. **Yinyin Xia** - Writing - review & editing. **Tao Kuang** - Data curation; Writing - review & editing. **Hua Zhang** - Writing - review & editing. **Yingxin Chen** - Writing - review & editing. **Ting-Li Han** - Writing - review & editing. **John Gulliver** - Conceptualization; Formal analysis; Methodology; Validation; Roles/Writing - original draft; Writing - review & editing.

## Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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## Appendix A. Supplementary data

Supplementary data to this article can be found online at <https://doi.org/10.1016/j.apr.2021.101096>.

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