

1 Flight altitudes of a soaring bird suggest landfill sites as power line collision hotspots

3 Abstract

4 Anthropogenic structures are increasingly encroaching wildlife habitats, creating conflicts between
5 humans and animals. Scaling up renewable energy requires new infrastructures such as power lines, that
6 cause high mortality among birds since they act as obstacles to flight and are used for perching and
7 nesting, which can result in collisions or electrocutions. These interactions often endanger wildlife
8 populations and may also result in high financial costs for companies. Flight behaviour plays a crucial
9 role in collision risk, and the study of flight altitudes enables us to understand what drives birds to fly at
10 collision risk altitudes. This allows the identification of high-risk areas, conditions and bird behaviours,
11 and the implementation of mitigation measures by power line companies. In this study, we use boosted
12 random tree modelling to identify drivers of white stork (*Ciconia ciconia*) flight altitudes and to
13 investigate the factors that lead them to fly at collision risk altitudes. We found that the main drivers of
14 flight altitude for this soaring bird species were time of day, distance to the nearest landfill site and cloud
15 cover density. Bird age, habitat type and season were comparatively less important. Collision risk
16 increases during crepuscular hours near landfill sites, also in days with high cloud cover density and
17 during the breeding season. In recent years, hundreds to thousands of storks congregate daily at landfill
18 sites to take advantage of the predictability and superabundance of anthropogenic food waste. Some of
19 these sites have high density of power lines, becoming collision risk hotspots for storks and other landfill
20 users. Despite being susceptible to collision, our results suggest that white storks can avoid power lines to
21 a certain extent, by changing their flight altitude at ca. 80m from these structures. This study shows that
22 the implementation of mitigation measures for existing power lines should be prioritised in areas in the
23 vicinity of landfill sites within white stork distribution ranges, and the projection of new lines should
24 avoid those areas. These measures would benefit species vulnerable to mortality due to power line
25 collision, and it would also reduce associated power outages and economic costs.

26 **Keywords:** collision risk, collision hotspot, power lines, landfills, flight altitudes, mitigation measures

28 1. Introduction

29 Anthropogenic disturbance of air space is increasing, creating conflicts between human infrastructures
30 and volant animals (Chilson et al., 2017), as is the case of birds. Along with wind turbines, buildings,
31 communication towers and aeroplanes, overhead power lines pose a threat to avian wildlife, not only
32 through collision and electrocution risk but also due to indirect impacts such as habitat changes, barrier
33 effects, and the disruption of typical movement patterns (Benítez-López et al., 2010; Chilson et al., 2017).
34 There is compelling evidence that these effects influence population dynamics (Chevallier et al., 2015;
35 Richardson et al., 2017), and can ultimately jeopardize the long-term population viability of many species
36 and populations (Benítez-López et al., 2010).

37 Worldwide, tens of millions of birds die annually due to power lines (Loss et al., 2015), making avian
38 collisions with these structures a global conservation concern (Jenkins et al., 2010). Nevertheless, bird
39 collision and electrocution also represent an economic concern to electricity companies by causing
40 electrical malfunctioning, short-circuits, outages and fires. For example, in Spain alone, it is estimated
41 that the economic impact of fauna mediated wildfires caused by power lines is of 170 to 280 thousand
42 euros per year (Guil et al., 2018). In Italy, a 16h-blackout in 2003 originated losses of more than 1.15
43 billion euros (Schmidthaler and Reichl, 2016), and in the United States, power outages are estimated to
44 cost 21 to 150 billion euros, annually (Peretto, 2010). Adding to the continuous increase in energy
45 demand, the shift towards renewable energy to combat climate change results in a further need for energy
46 infrastructures (Nies, 2019). Consequently, the electricity grid is growing at an annual rate of 5% (Jenkins
47 et al., 2010), which will certainly exacerbate human-wildlife conflicts, and increase the need to find
48 solutions that effectively reduce collision risks and associated economic costs.

49 A key challenge to reduce avian mortality rates driven by power line collision is to identify the factors
50 that influence birds' flight altitudes and to assess under which circumstances birds fly at collision risk
51 altitudes (Bernardino et al., 2018). This knowledge could be the basis for the identification and
52 development of appropriate management strategies that could be implemented by power line companies,
53 in order to decrease the likelihood of birds flying at collision risk heights in the vicinity of these
54 infrastructures. This would benefit both species conservation and corporations, by reducing costs related
55 to avifauna (Maricato et al., 2016) and promoting an environmentally friendly business (Moreira et al.,
56 2017).

57 Flight altitudes, and consequently bird collision risk is influenced by both extrinsic (site-specific and line-
58 specific) and intrinsic (species-specific) factors (Bernardino et al., 2018; Chilson et al., 2017; D'Amico et
59 al., 2018). Despite some evidence that birds may avoid power lines by adjusting flight altitudes upward
60 when approaching these obstacles (Luzenski et al., 2016), collision is not always prevented. Topographic
61 variations, habitat features, weather and light conditions, as well as anthropogenic disturbance levels are
62 considered site-specific factors; while line configuration, wire diameter and height are line-specific
63 factors of collision risk (Bernardino et al., 2018). Topography defines orographic and thermal uplifts,
64 with mountains and depressions providing different flyways for soaring and consequently, different flight
65 altitudes. Habitat features associated with different land uses such as vegetation density, should also
66 influence flight altitude, as open areas allow birds to fly lower than in forested habitats. Moreover,
67 foraging habitats are likely associated with lower flight altitudes as birds frequently approach and leave
68 these sites during their foraging trips. Strong winds, heavy rainfall, or fog may force birds to fly at lower
69 altitudes due to both little visibility conditions and absence of thermal updrafts, reducing individuals
70 ability to avoid collisions (Murphy et al., 2016b). Periods of low light levels such as twilight and night are
71 especially dangerous when flying at low altitudes due to reduced visibility (Murphy et al., 2016b).
72 Among intrinsic factors (species-specific), morphology, vision and behaviour can all be linked with
73 collision risk (Martin and Shaw, 2010). Wing loading, body weight and visual capacity influence species'
74 in-flight manoeuvrability, making large and heavy species with narrow visual fields more vulnerable to
75 unexpected obstacles (Rayner, 1988). Behavioural susceptibility to collision risk may be related to
76 nocturnal activity, migratory habits and gregariousness, as well as age, sex and health status (Bernardino

77 et al., 2018). During the breeding period, collision with power lines often occurs during daily movements
78 between foraging and nesting sites (Bernardino et al., 2018), when birds fly at lower altitudes and
79 increase landings and take-offs. Younger and more inexperienced birds, with lower manoeuvrability (e.g.,
80 Henderson et al. 1996) and less familiar with the landscape are likely to be at higher collision risk.
81 Finally, birds using power lines for hunting, resting, or nesting could also be more exposed to collision
82 risk.

83 The white stork (*Ciconia ciconia*) is a very adaptable, opportunistic species. In recent decades white
84 storks have established a unique relationship with the energy infrastructure (Moreira et al., 2017); this
85 species increasingly uses electricity pylons as nesting structures (Moreira et al., 2017), however, power
86 lines also cause high mortality rates by electrocution and collision (Garrido and Fernández-Cruz, 2003;
87 Kaługa et al., 2011; Schaub and Pradel, 2004). Mortality can occur in two different ways, electrocution
88 and collision. While electrocution is considered the main source of mortality for white storks (e.g. Schaub
89 and Pradel, 2004; Kaluga et al., 2011), collision events represent an important proportion of power line
90 driven mortality in the species (Garrido and Fernández-Cruz, 2003; Shaw et al., 2021), and as such, it
91 should be properly addressed. In Portugal, white storks' mortality rate driven by transmission power lines
92 alone is estimated at 11% of the breeding population, but these numbers are likely to increase in the
93 future, following the rapid population growth and the continuing expansion of the electrical grid (Moreira
94 et al., 2017).

95 White stork numbers are increasing in Iberia, which is widely attributed to their high resiliency and
96 behavioural plasticity to use landfill sites year-round (Gilbert et al., 2016). Estimates indicate that the
97 probability of this species attending landfill sites is of 60% and 44% during the non-breeding and
98 breeding season, respectively (Soriano-Redondo et al., 2021). Superabundance of anthropogenic waste
99 from landfills provide white storks with a spatially and temporally predictable food source that greatly
100 influences species activity and movement patterns, significantly reducing individual's foraging time and
101 range and ultimately enhancing overall breeding success and population growth rate (Arizaga et al., 2018;
102 Gilbert et al., 2016). Landfills are mostly located close to areas with high human population density, thus
103 likely to be associated with high presence and density of power lines. With thousands of storks travelling
104 to and from landfills to forage, especially on the breeding season to feed their offspring, these sites can
105 constitute hotspots of bird collision and significantly increase white stork mortality.

106 In this study, we use a large flight altitude dataset of white storks in Portugal to assess the risk of collision
107 for this species. To do so, we (1) identify and evaluate the relative importance of potential drivers of
108 flight altitudes as a proxy to collision risk, and specifically investigate if landfills can work as collision
109 hotspots for this species; (2) assess reaction distances and avoidance behaviour in response to power
110 lines; and (3) propose mitigation strategies to reduce the impact of power line associated mortality. To
111 fulfil our first objective, we model the influence of habitat type, distance to the nearest landfill, season,
112 age, cloud cover and time of day on flight altitude. Secondly, we use a smaller dataset on the flight
113 altitudes of storks near power lines to assess whether storks change their flight altitudes in the proximity
114 of these structures. Finally, we use the results of this study to propose measures to minimise mortality
115 associated with collisions with power lines.

116 **2. Materials and Methods**

117 *2.1 Bird capture and tracking*

118 For this study, we collated GPS data from 34 white storks (19 juveniles and 15 adults) tagged in 2017 and
119 2018. Storks were captured and tagged in four areas in central-southern Portugal, along with three landfill
120 sites (Fig.1). Juveniles were first-year birds tagged before fledging, while adults were breeding birds
121 (>3 years old). None of the birds nested on electricity pylons. We used two models of GPS/GSM
122 backpack loggers – Flyway 50 by Movetech Telemetry and Ornitrack-50 by Ornitela – that were attached
123 to the storks with a Teflon harness (Gilbert et al., 2016; Soriano-Redondo et al., 2020). Loggers were
124 programmed to transmit timestamp, position, and height with a frequency of ~20 min. See further details
125 on individuals' tagging year and location in Table S1 and detailed methods in supplementary material.
126 While adults were resident individuals overwintering in Portugal, all first-year juveniles migrated to
127 African winter grounds ca. 38 days after fledging. Juvenile data was consequently trimmed to only
128 account for the period between fledging and the moment they leave the Portuguese territory, as detailed
129 power line data was not available outside of Portugal. The fledging date was defined as the first day of
130 fledging after flying 50 meters away from the nest.

131 *2.2 Assessing storks' flight altitudes*

132 GPS tags from Ornitela and Movetech measure, respectively, the altitude above mean sea level and
133 altitude relative to the ellipsoid. The vertical accuracy of the GPS tags was ~10m (author's unpublished
134 data). To avoid losing precision associated with geoid undulation images resolution, we did not convert
135 height above the ellipsoid to height above sea level. Instead, flight altitudes above ground were calculated
136 by subtracting the ground elevation value from the height above the ellipsoid and by subtracting
137 orthometric height to altitudes measured above mean sea level. High-resolution ellipsoid and orthometric
138 topography images (30-meter resolution) were obtained from NASA Shuttle Radar Topography Mission
139 (Farr et al., 2007). All fixes with ground speed below 1.39m/s (Limiñana et al., 2012; Shamoun-Baranes
140 et al., 2011) were excluded from the analysis to select only for flight fixes. In-flight behaviour was further
141 supported by selecting measured heights above 5m and by discarding records less than 20 minutes apart
142 (Poessel et al., 2018). A detailed description of this section is provided in the supplementary material.

143 *2.3 Drivers of storks' flight altitude*

144 To determine the main drivers of flight altitude, we selected a range of potential variables (both intrinsic
145 and extrinsic factors) based on recent literature (Bernardino et al., 2018; Chilson et al., 2017) and
146 observed in-field behaviour of storks near anthropogenic structures. These included habitat type, distance
147 to the nearest landfill, season, age, cloud cover and time of day (Table 1).

148 Habitat type was classified as foraging versus non-foraging habitat since we expected that storks flew at
149 lower altitudes in foraging areas. Wetlands, agricultural areas and landfill sites were considered potential
150 foraging areas (Moreira et al., 2018). Habitat type was thus used as a binomial variable considering the
151 presence of flight fixes in foraging or non-foraging areas.

152 Distance to the nearest landfill was used as a predictor of flight altitude and defined as the Euclidean
153 distance from each white stork flight fix to the closest landfill centroid. Landfills provide an all-year
154 abundant food supply for storks and constitute important foraging areas during both the breeding and non-
155 breeding seasons (Gilbert et al., 2016). We expected storks to fly at lower altitudes close to landfills as
156 they approach them to feed and subsequently leave. To assess if landfill sites had higher powerline
157 presence compared to other areas, we randomly generated 50 points in the study area. We then compared
158 the power line presence in a 1km buffer around these sites and 11 landfills, using t-tests.

159 Season was divided into breeding season, between December (when adults start visiting and using nests
160 for extended periods) and July (when most juveniles leave the nests), and non-breeding season from
161 August to November. During the breeding season, adults make more trips between foraging areas and
162 nesting sites to feed their offspring (Henderson et al., 1996), likely flying at lower altitudes than during
163 the non-breeding season.

164 Age may also influence flight altitudes and consequently, collision risk, as juvenile birds probably have
165 inferior thermal soaring performance and more difficulty in adjusting fine-scale movements (Harel et al.,
166 2016). We hypothesize that juveniles fly lower than adults, with a larger proportion of collision risk
167 altitudes.

168 Cloud cover was the main weather variable which could directly impact both birds' visibility and thermal
169 uplift velocity (Mallon et al., 2016; Shamoun-Baranes et al., 2017). Thus, we used cloud cover as a proxy
170 of visibility and potential driver of flight altitude, as it could influence white storks to fly at lower
171 altitudes, closer to a collision risk altitude. Cloud cover at low altitude (<2km) was obtained from the
172 Environmental-Data Automated Track Annotation system (Dodge et al., 2013) and described as a
173 proportion of cloud covered cells, calculated based on surface pressure (Dee et al., 2011).

174 Time of day was used as a proxy of air temperature, light-dark cycle and thermal uplifts and defined at an
175 hourly base. As soaring birds, storks take advantage of atmospheric vertical air currents to fly without
176 spending much energy. These updrafts usually occur in the middle of the day when low masses of air
177 warm up and rise (Leshem and Yom-Tov, 1996). We found the time of day and thermal uplift variables to
178 be correlated ($r_s = -0.271$, $p < 0.0001$), and consequently the time of day was favoured due to the low
179 temporal granularity of thermal uplift data (every 6 hours). Data was filtered to only account for daylight
180 hours according to local time and season.

181 *2.4 Behaviour in response to power lines*

182 To analyse white storks' flight behaviour in the vicinity of power lines, we chose flight fixes at up to
183 300m of a power line and a maximum altitude of 156m (four times the maximum height of a power line),
184 as at higher altitudes there is likely no effect of power line structures on storks' flight altitude. We
185 assessed the electrical network on the Portuguese territory, a total of approximately 88,000 km (Fig.1),
186 and considered both transmission (high voltage lines that feed substations: 110 – 400 kV, 30 to 39 meters
187 of height) and distribution lines (medium voltage lines that feed the individual consumers: 6 – 60kV,
188 usually at 14 to 30 meters high) in the analyses. Distance to the nearest power line was defined as the
189 Euclidean distance from each white stork fix to the closest line. Previous studies show that birds react at a

190 ground distance beyond 25m from a power line (Brown and Drewien 1995, Murphy et al. 2016a).
191 However, to the best of our knowledge, there is no information on how far white storks see and respond
192 to the presence of overhead power lines. Thus, to be conservative, we defined 300m as the distance to
193 search for a reaction distance of storks.

194 2.5 Data analysis

195 We implemented gradient-boosted regression trees (BRT, Friedman 2001, De'ath 2007) to model (1) the
196 main drivers of storks flight altitude as a proxy of collision risk (with lower altitudes being associated
197 with higher collision risk) and (2) the effects of power line distance on flight altitude to look for
198 avoidance behaviour in the vicinity of overhead power lines. For the first model, we associated the
199 predictors habitat type, distance to the nearest landfill, season, age, cloud cover and time of day with stork
200 flight altitude fixes. For the second model, we used the same variables and included the distance to the
201 nearest power line as a predictor of flight altitude, using only fixes at a maximum of 300m from a power
202 line. BRT is a machine-learning method that offers several advantages over traditional regressions. This
203 method has recently been widely applied in ecological studies due to its high efficiency in handling
204 different types of variables (Fernandes et al., 2016; Leathwick et al., 2006; Moreira et al., 2018).

205 To reduce stochasticity caused by random sampling and bagging, we generated 100 BRT models and
206 averaged the relative importance of each predictor, presenting standard deviations. Model performance
207 was based on explained deviance and cross-validation correlation. After running initial exploratory
208 models, we found the distance to the landfill variable to have intricate patterns with no ecological
209 meaning, although it contributed to increasing model fit (see Fig S1). Such patterns usually occur when
210 complex interactions are allowed in the model (Elith et al., 2008; Leathwick et al., 2006), and it is a
211 common practice to impose a monotonic trend to variables in such situations (e.g. Leathwick et al. 2006,
212 Zhang et al. 2012, Moreira et al. 2017). Consequently, we refitted the models imposing a monotonic
213 decreasing trend to the distance to the landfill, as the trend of the unconstrained function matched the
214 monotonic version. To show the effects of each variable on flight altitude, we fitted partial dependence
215 plots by controlling for the other explanatory variables. Models were fitted in R (R Core Team, 2019)
216 using “gbm” and “dismo” libraries (Greenwell et al., 2019; Hijmans et al., 2017). For each set of models,
217 we calculated correlations (using Pearson correlation coefficient) and collinearity between predictors
218 (using variance inflation factor statistics) and assessed spatial autocorrelation in storks' flight altitudes.
219 We found no collinearity between predictors ($VIF < 1.05$) and no correlation between explanatory
220 variables ($|r| < 0.17$). We assessed spatial autocorrelation in model residuals through correlograms (100
221 runs) and took it into account using Residuals Autocovariate (RAC) approach (Crane et al., 2012).
222 Autocovariate was calculated through *autocov_dist* function from “spdep” package (Bivand and Wong,
223 2018) and was included in the BRT models.

224 3. Results

225 Individual white storks were tracked for an average of 180 days ($SD=220$) between 2017 and 2019, for a
226 total of 6116 tracking days (Adults: mean=360, min=41, max=680; Juveniles: mean=37, min=10,
227 max=65). Our tracking dataset included a total of 10,465 flight fixes (mean fixes/day 3.0 ± 1.3) with mean

228 flight altitudes of 212.39m (SD=251.9, min=5, max=1499). 26% (n=2685) of all flight fixes were in the
229 proximity of power lines (<300m). Landfill sites were found to have a higher presence of power lines
230 than random areas (t=4.4, df=49, p<0.0001).

231 *3.1 Drivers of storks' flight altitude*

232 Positive spatial autocorrelation was present in the model residuals, with maximum values within a 1.5 km
233 radius distance. Therefore, the value was used to compute the residual autocovariate (RAC). After
234 running the model including the autocovariate, the explained variance improved from 27% to 41%. RAC
235 became the most important variable, but the order of importance and the trend of the initial variables did
236 not change significantly compared to the first run (Fig S2). There was no significant spatial
237 autocorrelation in the residuals of the autocovariate-including model.

238 The BRT model for drivers of storks' altitude explained 25-27% of the total deviance with a correlation
239 coefficient of 0.47-0.48. Four of the six variables accounted for 90% of the explained variability. Time of
240 day was the most important variable, explaining 31.6±0.5% of flight altitude. Storks flew higher at
241 midday compared to the early morning and afternoon (Fig 2). Distance to the nearest landfill was the
242 second most important predictor in the model (relative importance (RI) ± standard deviation,
243 21.2±0.33%), showing that storks flew at lower altitudes when close to landfill sites, especially in a buffer
244 of 1km around it (Fig 2). Cloud cover and age had similar levels of importance in the model (RI:
245 20.4±1.10% and 17.6±0.39%, respectively). Flight altitudes decreased with higher cloud cover (Fig. 2).
246 Flight altitude was also influenced by age, with adults flying at lower altitudes than juveniles (on average
247 40m lower) (Fig. 2). Additionally, season (RI: 6.26±0.17%) and habitat type (RI: 2.89±0.11%) were the
248 least important variables in the model. Storks flew at lower altitudes during the breeding season and when
249 overflying foraging areas (Fig. 2).

250 *3.2 Behaviour in response to power lines*

251 Similarly to the results found in the first model, positive spatial autocorrelation was present in the
252 distance to power line model residuals, at up to 1.8km. Residuals autocovariate was computed at this
253 distance radius. After running the model including the residuals autocovariate, the explained variance
254 improved from 18% to 20%. The autocovariate was the second most important variable, but the order of
255 importance and the trend of the initial variables did not change significantly compared to the first run (Fig
256 S3). There was no significant spatial autocorrelation in the residuals of the autocovariate-including model.

257 The BRT model to evaluate flight behaviour in response to power lines explained 18-19% of the total
258 deviance, with a correlation of 0.35-0.36. Time of day was the most important variable describing flight
259 altitude, explaining 35.4±0.65% of the total variance, followed by the distance to the nearest power line,
260 distance to the nearest landfill and cloud cover, with similar values (17.8± 0.83%, 15.4± 0.32% and 14.2±
261 0.48%, respectively). Season (8.6± 0.21%), age (4.5± 0.10%) and habitat type (4.0± 0.07%) were the least
262 important explanatory variables. All the variables had similar shapes to the previous model (Fig 3). Storks
263 were found to promptly change their flight altitude at ca. 80m from power lines, flying higher to cross
264 them (Fig 3).

265 **4. Discussion**

266 Our results show ca. 25% of the white storks' flight locations are close to (<300 m) transmission and
267 distribution power lines. Moreover, 62% of the flight fixes near power lines were at collision risk
268 altitudes (between 5 and 49 meters, i.e., minimum, and maximum height of a power line, corrected for the
269 GPS altitudinal error of ± 10 meters). These findings highlight that white storks often fly at altitudes
270 presenting a high risk of collision, which has implications for power line managers, due to increased risk
271 of power outages and consequent economic costs.

272 We found that (ordered by relative importance) time of day, proximity to landfill sites, cloud cover, age,
273 presence on foraging habitats and seasons influence white storks' flight altitudes. Our model can be used
274 to derive an indicator of collision risk with power lines, enabling the identification of high-risk conditions
275 and areas.

276 Time of day was the most important variable found to influence flight altitude. White storks are soaring
277 birds and are consequently dependent on strong thermal convection to glide (Chevallier et al., 2010),
278 being most active during the day and resting at night. Thermals are more likely to form when solar
279 radiation at the earth surface is greatest, around mid-day (Leshem and Yom-Tov, 1996). Consequently, at
280 dusk and dawn, when there are fewer thermal updrafts, and the visibility is lower, white storks fly closer
281 to collision risk altitudes and are more prone to collide with power lines. Furthermore, often at dusk and
282 dawn, storks commute between foraging sites and the roosting or nesting sites, which can increase
283 collision risk in those areas. In fact, from 2016 to 2020, 56% of the white storks tracked by the authors
284 that died due to power line collision (n=9; unpublished data) perished during twilight and night hours.
285 Environmental conditions also influenced bird activities. As expected, cloud cover was associated with
286 decreased flight altitudes. Cloud cover can influence flight altitudes not only through limiting visibility
287 during twilight hours and in foggy days, but also through lower uplift velocities. This behaviour is
288 described for other soaring birds such as turkey vultures (*Cathartes aura*) and black vultures (*Coragyps*
289 *atratus*), that tend to engage less in thermal soaring when cloud cover is high (Mallon et al., 2016), and
290 consequently, fly at lower altitudes.

291 Distance to the nearest landfill was the second most important variable in the model. Landfills are key
292 foraging areas for white storks, and lower flight altitudes recorded within these areas are likely a
293 consequence of an increase in the number of take-offs and landings. Landfill sites are often associated with
294 a high presence of power lines in the vicinity, as most are located close to peri-urban and urban areas, thus
295 increasing the risk of collision with these infrastructures. In Iberia, thousands of storks heavily rely on
296 anthropogenic food subsidies across the annual cycle and the predictability and superabundance of this
297 resource at landfills is considered responsible for the increase of the number of resident birds, that no longer
298 migrate to their African wintering grounds (Catry et al., 2017; Gilbert et al., 2016, Soriano-Redondo et al.,
299 2021), as well as for the overall rapid increase of population growth. In this sense, landfills may act as
300 ecological traps for storks by attracting birds to areas with a higher risk of mortality (Plaza and Lambertucci,
301 2017). Beyond collision, there is evidence of high electrocution risk (Garrido and Fernández-Cruz, 2003)
302 and anecdotal evidence of massive electrocution events in power lines around landfill sites. In 2003, two
303 large power line mortality events occurred in landfill sites in Spain, causing the death of 125 and 60 white

304 storks in one day (ABC, 2003a, 2003b). Furthermore, from 2016 to 2020, ca. 42% of white storks tracked
305 by the authors that died on power lines (both from collision and electrocution) were close to landfills
306 (<1km). The same pattern found for landfills is also likely to occur in other important feeding habitats, such
307 as rice fields and wetlands as storks flew at lower altitudes when close to foraging habitats, compared to
308 non-foraging habitats. During the breeding season, adults make additional foraging trips from these sites to
309 the nest to feed their offspring, also supporting the observed lower flight altitudes during this season..

310 Previous studies showed that juvenile birds are more prone to collision than adults (Jenkins et al., 2010;
311 Sundar and Choudhury, 2005), and have higher mortality rates caused by power lines (Garrido and
312 Fernández-Cruz, 2003; Schaub and Pradel, 2004). Therefore, we expected that juvenile storks flew more at
313 collision risk altitudes than adults, but found the opposite. A possible explanation for this unexpected
314 finding is that although flying, on average, at higher altitudes (soaring), when approaching power lines,
315 inexperienced birds are less able to avoid collision due to their lower manoeuvring skills and less efficient
316 flight behaviour (Harel et al., 2016; Rotics et al., 2016), as flying at lower altitudes requires more flapping
317 and manoeuvrability.

318 White storks have one of the highest mortality rates caused by power lines in Europe (Garrido and
319 Fernández-Cruz, 2003; Kaługa et al., 2011; Moreira et al., 2017; Schaub and Pradel, 2004). In this work,
320 we addressed the potential drivers of collision risk. Several characteristics make white storks highly
321 vulnerable to collisions, as they are large birds with limited manoeuvrability, limited binocular fields and
322 large blind areas (D'Amico et al., 2018; Martín and Shaw, 2010). Nonetheless, our results suggest that
323 storks can avoid power lines to a certain extent and can reduce collision risk. When encountering power
324 lines, storks appear to see the wires and avoid them by adjusting flight altitudes upward ca. 80m before
325 reaching them. Even so, at that distance, because storks fly at an average speed of 10m/s when close to
326 the reaction distance (80-150m), they only have 8s to change flight altitude and avoid collision, a short
327 period considering their size.. Due to their low in-flight manoeuvrability, white storks' capacity to adjust
328 paths to avoid power lines is very limited and primarily constrained by thermal uplift conditions, cloud
329 cover and in specific circumstances of low sunlight, visibility, and high densities of lines. Previous
330 studies showed observed in-field birds reaction to power lines beyond 25m (Brown and Drewien, 1995;
331 Gális and Ševčík, 2019; Murphy et al., 2016a). To our knowledge, this is the first time we estimate a
332 specific value of reaction distance of white storks to power lines. Endorsing this result, we observed that,
333 when in the presence of transmission power lines (30 to 39m of height), storks flew higher than when
334 close to lower distribution power lines (14 to 30m of height) (see Fig S4).

335 *4.1 Implications on mitigation measures and future perspectives*

336 Conflicts between roaming wildlife and humans are likely to increase with the current rapid economic and
337 human population growth (Jenkins et al., 2010; Tucker et al., 2018). The number of anthropogenic
338 structures, such as buildings, wind turbines, and power lines, across the globe is increasing, with major
339 consequences for population viability of birds (Chevallier et al., 2015; Jenkins et al., 2011). Although a
340 shift towards renewable energy is essential, it also requires the construction of further power line
341 infrastructures, possibly exacerbating the negative impacts for wildlife. In the light of the Paris
342 Agreement Compatible Scenarios for Energy Infrastructure goals and the Renewables Grid Initiative,

343 which aims to find common grounds between companies, scientists and environmental organizations
344 (Nies, 2019), the results obtained in this study have direct implications in terms of solutions for
345 infrastructure management and the implementation of mitigation measures.

346 Landfill sites were found to be high-risk areas for collision. Consequently, mitigation measures applied to
347 power lines at less than 1km of landfill sites should be considered as a priority to reduce collision of white
348 storks, and simultaneously, the power outages and the associated economic costs. Storks form flocks of
349 thousands of individuals in landfills, often flying at low altitudes from there to the nests in the breeding
350 season, or between roosts and landfills during the non-breeding season at dawn or dusk, making these
351 areas highly-prone to stork collisions (Garrido and Fernández-Cruz 2003). The best practice to prevent
352 bird collisions with power lines in close proximity to landfill sites would be to bury existing power lines
353 and use underground cabling for new structures (Marques et al., 2020), as power line marking is not
354 efficient enough in preventing collisions (Bernardino et al., 2019). This encompasses much higher costs
355 (Bernardino et al., 2018; Hall, 2013) than traditional overhead power lines, thus we recommend its
356 implementation only within 1km of landfill sites. Alternatively, existing power lines could be potentially
357 re-routed away from these areas, whenever possible, at a lower cost.

358 Moreover, measures that promote the visibility of power lines at a distance, in hours of low visibility,
359 should be implemented in most important breeding and foraging areas, and particularly, in the
360 surroundings of landfill sites. Several types of bird flight diverters (e.g. spirals, plates, swivels) have been
361 used to increase the visibility of power lines (Barrientos et al., 2011; Jenkins et al., 2010; Pavón-Jordán et
362 al., 2020), decreasing bird collision at an average of 50% (Bernardino et al., 2019), although with varying
363 effectiveness across species. Glow-in-the-dark devices, with higher detectability at twilight, should be
364 prioritized and their effectiveness tested. Finally, although we did not address electrocution risk in this
365 work, securing poles against electrocution around landfill sites is also essential, as electrocution is a
366 critical cause of death for white storks (Kaluga et al., 2011).

367 In this study, we did not assess the influence of power line structure-specific characteristics. Nevertheless,
368 the effect of power line wire configuration in collisions is dependent on flight altitudes, and
369 configurations with multiple levels of wires will increase the collision risk area, posing a higher threat to
370 birds. The development of movement sensors to detect collisions of tracked birds proposed by Bernardino
371 et al., 2018 would significantly help to identify power line sectors in which birds are more prone to
372 collision and consequently to prioritize other areas in which mitigation measures should be implemented.

373 *4.2 Study considerations and limitations*

374 In this study, thermal and orographic updrafts explain the time of day as a primary driver of flight
375 altitudes for soaring birds. More complex models used to predict flight altitude would require high-
376 resolution spatial and temporal data on topographic features, weather conditions and visibility, which are
377 rarely available at a small-time scale for long study periods. Although the GPS devices used in this study
378 had minor location error (<5m) in a horizontal plane (authors' unpublished data), altitude measurement
379 errors had to be taken into consideration (Péron et al., 2020; Poessel et al., 2018). Almost 34% of our
380 original flight records were below ground values, a value considered as typical for flight height data

381 (Péron et al. 2017). We addressed this issue by removing fixes below a threshold (Poessel et al., 2018;
382 Shamoun-Baranes et al., 2011) of 5m above ground level. Furthermore, the flight altitude estimation error
383 should not influence the results of this study, as we do not evaluate specific flight altitudes, but the
384 difference among them.

385 4.3 Conclusions

386 We show that, for the white stork, the worst condition scenario for power line collision would be flying
387 near landfills, at dusk and dawn, with high cloud cover, during the breeding season. Landfills were found
388 to be collision hotspots for this species. Although white stork populations are well established and
389 expanding in Europe (Newton, 2007), the increased use of power lines as nesting sites (Moreira et al.,
390 2018) and landfills to forage (both considered collision and electrocution hotspots) makes urgent the
391 implementation of mitigation measures to reduce mortality caused by power lines, as landfills could
392 potentially be acting as ecological traps for this species. These measures would benefit other bird species
393 with poor conservation status and high power line-associated mortality rates, as well as other species that
394 frequently use landfills, such as the threatened Egyptian vulture (*Neophron percnopterus*) (Tauler-
395 Ametller et al., 2017), kites and gulls. Collaboration between industry partners, scientists and
396 environmental organisations is vital to ensure that the ongoing powerline grid expansion is not
397 detrimental to wildlife. In a win-win scenario, biodiversity conservation would coincide with the
398 minimization of economic costs for infrastructure companies and the promotion of a biodiversity-friendly
399 attitude (Bernardino et al., 2018; D'Amico et al., 2018).

400 Acknowledgements

401 This work was financed by the FEDER Funds through the Operational Competitiveness Factors Program
402 — COMPETE and by National Funds through FCT – Foundation for Science and Technology within the
403 scope of the project ‘POCI-01-0145-FEDER-028176’, by InBIO (UID/BIA/50027/2013 and POCI-01-
404 0145-FEDER-006821), with support from the REN Biodiversity Chair, and by the National Environmental
405 Research Council (NERC), via the EnvEast DTP, and NERC and Engineering and Physical Sciences
406 Research Council (EPSRC), via the NEXUSS CDT Training in the Smart and Autonomous Observation of
407 the Environment. Funding for the development of the GPS tracking devices was provided by NERC (NE/
408 K006312), Norwich Research Park Translational Fund, University of East Anglia Innovation Funds and
409 Earth and Life Systems Alliance funds. J.M was supported by a doctoral grant (SFRH/BD/114683/2016)
410 and I.C., J.P.S. and F.M. by contracts DL57/2016/CP1440/CT0023, DL57/2016/CP1440/CT0021 and
411 IF/01053/2015, respectively, from FCT.

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605 **Table for the manuscript:**

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Variable	Description	Descriptive Statistics (mean±SD, min, max)	
		Flight altitude drivers	Avoidance behaviour
Habitat	Foraging (wetlands, agricultural areas, landfill sites);	F: 8163 obs.	F: 2159 obs.
	Non-foraging (Forest, water bodies, shrublands)	NF: 2302 obs.	NF: 526 obs.
Distance to landfill	Distance (km) to the closest landfill	12.2±11 (0.01, 51.77)	6.9±8.0 (0.01, 47.6)
Season	Breeding (December - July);	B: 8720 obs.	B: 2212 obs.
	Non-breeding (August - November)	NB: 1745 obs.	NB: 473 obs.
Age	Adult (> 3 years);	A: 7756 obs.	A: 2262 obs.
	Juvenile (1st year)	J: 2709 obs.	J: 423 obs.
Cloud cover	The proportion of the model grid cell covered by cloud occurring in low levels of the troposphere (0-1)	0.08±0.17 (0, 0.99)	0.1±0.18 (0, 0.99)
Time of day	Hour of day (hourly)	13±3 (4, 20)	12.5±3.5 (4, 20)
Distance to power line	Distance (m) to the closest power line	-	146.1±83.1 (0.18, 299.98)

607 **Table 1.** Description and descriptive statistics (mean, standard deviation, minimum and maximum values) of the
608 explanatory variables for the flight altitude drivers and avoidance behaviour near power lines models.