Profiles of katabatic flow in summer and winter over Coats Land, Antarctica

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SUMMARY

Observations from a novel autonomous Doppler sodar wind profiling system are described and analysed. These include the first continuous wintertime soundings of katabatic winds over Antarctica—a continent with which they are synonymous. During 2002 and 2003 over 2600 wind profiles were taken during 'case-studies' of high-resolution sounding lasting hours to days. These case-studies have been subjectively classified as: synoptically driven, katabatically influenced (28 days); primarily katabatically driven flows (a subset of 16 days); or other flow types. The Doppler sodar observations were augmented by automatic weather station observations at the field site and further up the slope, as well as synoptic and upper-air observations at Halley Research Station, some 50 km distant on the Brunt Ice Shelf.

In primarily katabatic flows there is a systematic change in the shape and depth of the low-level katabatic jet with wind speed. Relatively strong katabatic flows (maximum winds of typically 8–10 m s⁻¹) have a jet maximum between 20 and 60 m above the surface and are relatively deep (up to 200 m); while moderate katabatic flows (4–8 m s⁻¹) typically have a jet maximum between 3 and 30 m and are shallower (~100 m), although they can also be more diffuse in structure with a wind speed maximum at higher altitude. In all katabatic flows there is backing of wind direction with height, consistent with decreasing friction away from the surface. During summertime katabatic flows there is a clear diurnal signature at all heights, although this is less pronounced in the surface layer where there seems to be a persistent 2–4 m s⁻¹ katabatic flow during all case-studies. Where the diurnal forcing results in an abrupt katabatic flow deceleration, i.e. what may be a katabatic 'jump', there is a concurrent vertical acceleration. Wind profiles from a recent numerical weather prediction study of idealized katabatic flows at this site compare favourably with selected mean profiles; the only significant difference is that the model's wind speed is too low over the lowest ~10 m.

KEYWORDS: Doppler sodar Hydraulic jump Katabatic winds Low-level jet

1. INTRODUCTION

Katabatic flows are downslope buoyancy-driven flows. The domed topography and high-latitude locations of Antarctica and Greenland lead to a radiative cooling to space during the polar winter, and means that katabatic flows are ubiquitous over these regions. The basic physical process is as follows. A long-wave radiative loss to space leads to cooling of the snow surface and a compensating downward sensible-heat flux, which cools the atmospheric surface layer and forms a temperature inversion. In the presence of a slope, this induces a horizontal temperature (i.e. buoyancy) gradient, equivalent to a downslope horizontal pressure-gradient force, i.e. a katabatic force. The widespread nature of katabatic flows over Antarctica means that they contribute to the general atmospheric circulation of the southern hemisphere (e.g. Parish and Bromwich 1991, 1998). In addition, on reaching the coast katabatic flows interact with sea ice, polynyas, or the coastal ocean, thus playing a part in water mass conversions and the thermohaline circulation. In short, they are key components of the high-latitude climate system.

Observations of widespread katabatic flows, such as those over Antarctica and Greenland, have always been compromised by the obvious technical and logistical challenges of observing in extremely cold and remote environments. The earliest studies of Antarctic surface winds relied on patterns left in the snow (e.g. sastrugi) to infer climatological surface winds (e.g. Mather and Miller 1967) or were limited to manned observing stations (Lettau and Schwerdtfeger 1967). Subsequently automatic weather

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stations (AWS) provided the means to obtain a high temporal-resolution year-round picture of the surface winds and, although numerous technical problems have been endured, these remain a mainstay of katabatic-flow studies (e.g. Parish 1988; Stearns and Wendler 1988; Bromwich 1989; Pettré and André 1991; King 1993; Renfrew and Anderson 2002) their main limitation being that the height of the AWS mast (typically 3 m) usually allows only one level of near-surface wind measurement.

Observations of the vertical structure of katabatic flows are rare. The manned research stations in both Greenland and Antarctica are mainly around the coast on islands, ice shelves or nunataks, and naturally these tend to avoid areas prone to katabatic winds. The few manned stations in the interior (e.g. Amundsen-Scott at the South Pole, Dome C, Vostok) tend to be on very slight slopes, or plateaux, where any katabatic forcing is very weak. This means that observational studies of katabatic flow structure thus far have been remotely based field experiments and so have been restricted to the summer months.

Over Greenland and Antarctica, intensive field experiments have been carried out using aircraft, tethersondes, radiosondes and sodar, usually augmented by surface observations from AWS. For example, at the western margins of Greenland, van den Broeke et al. (1994) used tethersonde observations and Meesters et al. (1997) used mast and sodar observations to describe the average structure of katabatic winds during summer conditions. Over western and eastern Greenland, Heinemann (1999, 2002) used a research aircraft to obtain numerous soundings of early summer katabatic flows and, due to the comprehensive sampling carried out, was able to quantify the momentum budget of the flow and its turbulent structure. Over Adélie Land, in Antarctica, as part of the IAGO (Interaction Atmosphere-Glace-Ocean) campaign, Sorbjan et al. (1986) and Pettré and André (1991) used tethersonde and radiosonde observations to describe the summertime atmospheric boundary layer. Near Siple Coast, Bromwich and Liu (1996) used sodar, a radio acoustic sounding system and radiosonde soundings to describe summertime katabatic flows; while over Dronning Maud Land, Bintanja (2000a,b) combined simultaneous tethersonde and radiosonde soundings to calculate an approximate momentum budget of summertime katabatic flow. Outside of these few intensive but short-lived summertime field campaigns there are relatively few observations of the vertical structure of katabatic flow in Antarctica (e.g. Ohata et al. 1985) or Greenland.

This paper presents extensive year-round observations of the vertical structure of katabatic flow over Coats Land, Antarctica from 2002 and 2003. The wind profiles are derived from an autonomous Doppler sodar sounding system installed on a moderate slope some 50 km south of Halley Research Station. The moderate uniform slopes of Coats Land are typical of much of coastal Antarctica, suggesting these observations are representative of katabatic winds on similar slopes around the continent. The wind profiling system could not be run continuously due to power supply limitations. Instead, 'case-study' periods of a few hours to days were sampled, chosen on the basis of real-time meteorological information provided by an in situ AWS. The Doppler sodar system sampled continuously during these periods, thus providing a wealth of data for a selection of cases, allowing a comprehensive picture of the temporal variability of the katabatic flows and amassing a large number of wind profiles without the labour of a tethersonde or radiosonde system. A total of over 2600 vertical wind profiles were observed over the 2-year period. Significant observational periods have been subjectively classified as: synoptically driven, katabatically influenced (28 days and 1626 profiles); or primarily katabatically driven flows (a subset of 16 days and 805 profiles); or other flow types.



Figure 1. Topographic map of Coats Land, Antarctica, based on the Antarctic Digital Database version 3 (BAS 1993). The contour interval is 100 m. The location of Halley Research Station is shown, and the four automatic weather station sites are marked C1 to C4. The autonomous Doppler sodar was deployed at C2 during 2002 and 2003.

In the next section further details on the Coats Land experiment, a summary of Coats Land's surface climatology and a brief description of the autonomous Doppler sodar system are presented. In section 3, two katabatic flow case-studies (one from summer and one from winter) are described and used to illustrate the profile data. In section 4, a composite analysis of the vertical structure of primarily katabatic flow is carried out, while section 5 presents conclusions.

2. THE COATS LAND EXPERIMENT

Coats Land lies in the Weddell Sea sector of Antarctica. Figure 1 shows a topographic map of the area, based on the Antarctic Digital Database version 3 (BAS 1993). The location of Halley and four AWS sites (C1 to C4) are marked. Table 1 notes some geographical details of the sites. The slopes of Coats Land consist of a snow-covered ice sheet which is uniform across and modest in gradient (around 5% at most), relative to the Antarctic continent in general. The coastline is typical of much of the moderate slopes of the continent. The proximity of Coats Land to the British Antarctic Survey's Halley research station, on the Brunt Ice Shelf, suggests it as an ideal location to study 'ordinary' Antarctic katabatic flows, i.e. those that develop on relatively modest, uniform slopes (as opposed to the 'extraordinary' katabatic flows found over very steep or convergent topography, e.g. Bromwich (1989) and Wendler *et al.* (1993)). The Coats Land experiment ran from 1996 to the end of 2004, with AWS located at various sites over this period (for more details see Renfrew and Anderson 2002; Anderson *et al.* 2005).

A description of the surface climatology of Coats Land based primarily on AWS and Halley surface observations, but augmented with satellite products and upper-air radiosonde soundings, is documented in Renfrew and Anderson (2002). They describe two dynamical regimes in the region: over the ice shelf near-surface winds were usually

Station	Latitude (°S)	Longitude (°W)	Height (m)	Slope (%)	Fall line	Distance from Halley (km)	Distance to downslope station (km)
Halley	75.60	26.20	37	0.07	155	0	-
C1	75.88	25.49	43	0.7	160	37	37
C2	75.96	25.41	400	5.5	165	46	10
C3	76.70	24.53	1400	1.0	150	132	86
C4	76.81	23.50	1650	0.8	145	155	32

TABLE 1. Geographical data for Halley and the Coats Land automatic weather stations, C1 to C4 $\,$

After Renfrew and Anderson (2002).



Figure 2. Wind roses for Halley and automatic weather stations C2 and C4: (a) for all matching wintertime observations during the period 1996–2000, and (b) during katabatic conditions at C2, as determined by conditional sampling. The wind directions are divided into 30° bins, and the wind speeds into 5 m s⁻¹ bins from 0.1 to 30 m s^{-1} . The size of the centre circle is proportional to the number of calm observations. The wind roses are plotted over the topography as shown in Fig. 1. (From Renfrew and Anderson 2002.)

from the east, occasionally from the west; whereas over the Coats Land slopes winds were from the east-to-south quadrant (Fig. 2(a)). Excluding the summer months, the surface layer over the ice shelf was about 10 K colder, in terms of potential temperature, than over the continent and was more stable than on the steepest part of the slope.

Motivated by case-studies and theoretical arguments, Renfrew and Anderson (2002) used a conditional sampling method to select a subset of the AWS data the members of which are, in some sense, katabatic^{*}. Examining these data (Fig. 2(b)), the authors showed that these archetypal katabatic winds flow from around 10° to the east of the fall line and with near-surface wind speeds of 7.5 m s⁻¹ at the C2 site (the steepest part of the slope), 5.1 m s^{-1} at the C3 site, and 3.8 m s^{-1} at the C4 site. They found no coherent surface katabatic-flow signature over the Brunt Ice Shelf—an aspect of the local climate also discussed by King (1993). King *et al.* (1998) used satellite remote sensing to infer a change in the temperature structure from the Brunt Ice Shelf to the slopes of Coats Land. This was investigated further by Renfrew and Anderson (2002) who found that during katabatic conditions potential temperatures over the ice shelf were also, on average,

^{*} The selection procedure chooses wintertime data where the perturbation pressure gradient between the AWS and Halley is small and the surface-layer stability is large—see Renfrew and Anderson (2002) for details.

some 10 K lower than over the continent. They therefore hypothesized that a damming, due to this pool of cold air in the ice shelf boundary layer, was causing the katabatic winds flowing from the continental slopes to ride over the boundary layer and/or be dissipated in some way as the flow decelerates (e.g. Ball 1960; Gallée and Schayes 1992; Gallée and Pettré 1998; Heinemann 1999). This hypothesis was confirmed by a momentum budget analysis in the numerical modelling study of Renfrew (2004).

According to this surface climatology, the AWS site subject to the strongest katabatic flows was C2; while according to the idealized numerical modelling of Renfrew (2004), the area of strongest katabatic winds stretched from just below C3 to just below C2. For this reason the C2 site was chosen for the installation of the Doppler sodar wind profiling system; the aim was to observe the vertical structure and variability of katabatic flows within a relatively dense (at least for the Antarctic) regional observing network.

The autonomous Doppler sodar wind profiling system was deployed at the C2 site for a subset of the full study period: namely 2002 and 2003. Prior to deployment the system was developed and tested in the UK and in Antarctica at Halley. The wind profiling system was based on a multi-frequency phased-array sodar, able to transmit acoustic pulses in several directions and hence use Doppler technology to calculate a three-dimensional wind profile from the acoustic returns. The sodar was powered by a parallel series of modules, each containing batteries, photovoltaic solar panels and vertical-axis wind generators, along with charging control and isolation circuitry. Unfortunately the wind generators failed during 2002, consequently there was only the stored battery power during the unlit winter of 2003. The main sodar processing unit was local to the antenna at the C2 site, but a radio telemetering system was devised to allow remote operation and data download from Halley (50 km to the north) via controlling software on a PC. An AWS was integrated into the system to provide realtime meteorological observations from the experimental site. Figure 3 shows the C2 site after the initial deployment of the autonomous Doppler sodar in January 2002. A detailed description of the system design and an evaluation of its performance can be found in Anderson et al. (2005).

A number of range-gate, pulse-frequency and pulse-duration settings were tried during the test phases of the experiment and, as with all sodar equipment, there was a trade-off between higher signal-to-noise ratios (achieved through longer pulse durations) and higher vertical resolution (achieved through closer range gates). In the end two settings were used during deployment in Coats Land: setting 502 (high vertical resolution) with range gates of 10 m from 20 to 60 m, 20 m from 60 to 120 m, 30 m from 120 to 210 m, 40 m from 210 to 330 m, 50 m from 330 to 430 m, and 70 m from 430 to 500 m; and setting 506 (standard vertical resolution) with range gates of 20 m from 20 to 100 m, 30 m from 100 to 220 m, 40 m from 220 to 340 m, 50 m from 340 to 440 m, and 60 m from 440 to 500 m. The frequencies and pulse durations prescribed can be found in Anderson et al. (2005). An analysis of data quality as a function of height showed a monotonic decrease with each successive range gate; in other words, using the 502 setting gave better vertical resolution at the expense of range, while using the 506 setting compromised resolution for a longer range (Anderson et al. 2005). According to the design specification of the Doppler sodar, wind accuracies are in the ranges: 0.1– 0.3 m s^{-1} for horizontal wind speed, $2-3^{\circ}$ for wind direction, and $0.03-0.1 \text{ m s}^{-1}$ for vertical wind speed, depending upon the prescribed settings. Qualitative comparisons against tethersonde wind profiles are discussed in Anderson et al. (2005).

The autonomous Doppler sodar system was designed to allow sounding for casestudy periods (or intensive observing periods) of a few hours to a few days. Continuous operation of the system was not possible due to power supply constraints. Therefore a



Figure 3. Photograph of the autonomous Doppler sodar wind profiling system situated at the C2 automatic weather station (AWS) site south of Halley in January 2002, looking towards the south-east. To the left is the sodar antenna, raised around 2 m above the snow surface; to the right, arranged in three rows, are the ten solar panels and ten wind generators that are part of the power system. Pointing towards the camera is the radio antenna. Behind the solar panels is the mast of the integrated AWS, with the propeller-vane anemometer on top. Out of shot are two other independent AWSs (from Anderson *et al.* 2005).

sounding strategy was developed to try and capture as many periods of meteorological interest as possible. To determine whether to start a sounding episode, the Halley sodar operators addressed two questions: (i) is there adequate power, and (ii) are the meteorological conditions interesting?

The power available to the system was monitored via the battery input voltage which, along with other power measurements, was transmitted with the AWS observations every hour from the remote site to Halley. Meteorological conditions of interest were, essentially:

- Periods of primarily katabatic flow;
- Transitions into or out of katabatic flow; and
- Periods of synoptically influenced katabatic flow.

Table 2 summarizes the specific meteorological criteria for each of the above three scenarios, as devised before the experiment. These criteria are based on the climatological and case-study analyses of Renfrew and Anderson (2002).

The priority before the experiment was to obtain several case-study periods of each scenario, with a particular priority being wintertime katabatic flow due to the scarcity of such data from anywhere in Antarctica. Indeed, for this reason no soundings were carried out during March and April 2003, instead the battery power was saved until the winter months of May to September. In addition to the above criteria, a preliminary analysis of the data was possible because the sounding data were transmitted back to Halley, and that analysis was then able to inform any modifications to the sounding strategy. Obviously a regular correspondence between the sodar operators at Halley and the research scientists working in the UK was maintained throughout the 2-year experiment.

Scenario	Description	C2 criteria	Halley criteria	
А	Wintertime katabatic flow	$5 < \text{wind speed} < 10 \text{ m s}^{-1}$ 120 < wind direction < 180° 'clear skies' observed <i>or</i> clear satellite image	Cloud < 3 octas sun below horizon	
В	Summertime katabatic flow	As A	As A, except sun above horizon	
С	Calm to katabatic flow transition	Initially: $0 < wind speed < 5 \text{ m s}^{-1}$ becoming: as A	Cloud < 3 octas 0 < wind speed < 5 m s ⁻¹	
D	Synoptic-scale low to katabatic flow transition	Initially: $10 \text{ m s}^{-1} < \text{wind speed}$ $60 < \text{wind direction} < 150^{\circ}$ becoming: as A	$10 \text{ m s}^{-1} < \text{wind speed}$ $60 < \text{wind direction} < 120^{\circ}$ becoming: as A	

 TABLE 2.
 METEOROLOGICAL SOUNDING CRITERIA BASED ON REAL-TIME SURFACE OBSERVATIONS

 FROM THE C2 AUTOMATIC WEATHER STATION SITE AND HALLEY RESEARCH STATION

Halley is a synoptic and upper-air meteorological observing station, so standard meteorological variables are recorded continuously and cloud observations every 3 hours. The C2 site, around 50 km to the south and on the continental slope, is visible during clear-sky conditions and daylight hours, so 'clear skies' there can be seen from Halley. In addition, a satellite receiving system could be checked for the regional cloud cover.

Table 3 provides an overview of the katabatic flow observations obtained from the Doppler sodar system during its deployment in Coats Land. The table does not include very short periods of data (less than a few hours), nor periods where the range was very poor, nor periods of system testing. In total there are 28 days of sounding during what could be described as katabatically influenced flow; these comprise 1626 vertical wind profiles (each a 15-minute average), with 655 of these using setting 502, and 971 using setting 506. Mean vertical ranges for each day were between 68 and 221 m (Table 3), with the 506 setting giving a slightly better range, as expected. The maximum wind speed for each profile was determined and then averaged over each period to give a simple measure of the strength of flow; these mean (maximum) wind speeds ranged from 2.6 to 8.5 m s⁻¹. As noted by Anderson *et al.* (2005) the Doppler sodar does not work for wind speeds much higher than ~ 12 m s⁻¹, due to contamination by wind-induced noise around the antenna. Also included in Table 3 are free-atmosphere observations of stability, potential temperature, wind speed and wind direction calculated as 400-1000 m averages of the 12 UTC* radiosonde soundings at Halley on that day. Given that the Doppler sodar site is 400 m above sea level, these should be broadly representative of the free atmosphere there since katabatic flow periods will tend to have weak baroclinicity.

3. Two case-studies of katabatic flow

Here two periods of predominately katabatic flow are illustrated and briefly discussed. Many more periods have been examined and are being studied further in conjunction with numerical modelling experiments, so further interesting facets of these case-studies will be reported in due course.

(a) A case of summertime katabatic flow

Figure 4 shows a time series of horizontal wind vectors against height from the Doppler sodar for 23 February 2002, a day of primarily katabatic flow. Wind vectors are plotted every 15 minutes at the central height of each sounding layer (in this case 30, 50, 70, 90, 115, 145, 175, 205 m, etc). Also plotted every hour (at 3 m) are the AWS wind

^{*} Note that times are given as UTC, whilst local time is about 1 h 40 minutes behind.

FABLE 3.	AN OVERVIEW OF THE	DOPPLER SODAR WIND	PROFILING PERIODS	WHERE SIGNIFICANT
	OBSERVATIONS OF KA	TABATIC FLOW OVER TH	e C2 site were obta	AINED

					Free atmosphere observations at Hall					
	Times	Sodar	Vertical range (m)		maximum wind speed	Stability	Potential temperature	Wind speed	Wind	
Date	(h)	setting	mean	median	$(m s^{-1})$	$({\rm K} {\rm m}^{-1})$	(K)	$(m s^{-1})$	direction	
2002										
22 February K	00–24	506	120	100	6.53	0.006	272	3.0	107	
23 February K	00–24	506	125	100	5.20	0.004	272	4.5	223	
24 February K	00–24	506	191	190	3.90	0.002	272	6.6	224	
25 February	00–24	506	200	190	4.20	0.009	272	3.5	226	
26 February	00–24	506	140	100	4.33	0.006	272	4.9	13	
27 February	00–24	506	170	160	2.60	0.006	272	1.4	0	
24 March	13–24	502	146	80	6.03	0.012	262	4.1	270	
25 March	00–24	502	68	60	6.33	0.011	265	3.3	39	
18 April	17-24	502	88	80	6.59	0.010	272	4.6	84	
19 April	00–24	502	136	120	4.11	0.013	271	3.4	210	
4 September K	14–18	506	183	160	4.32	0.022	261	3.2	146	
12 September	11-24	502	208	180	2.76	0.017	262	2.8	141	
18 September	11–24	502	165	150	6.00	0.010	265	_	_	
12 October K	09–24	502	69	60	5.20	0.003	266	3.4	207	
13 October K	00–09	502	111	90	2.86	-	_	-	-	
2003										
18 May ^K	11-17	506	124	100	7.84	0.013	264	4.0	130	
24 June	10-24	506	198	220	7.69	0.019	262	5.4	111	
25 June	00–09	506	171	190	6.37	0.017	268	3.0	136	
14 August K	10-16	506	125	100	4.97	-0.001	256	5.0	239	
28 August K	12-21	506	123	100	8.12	0.016	264	5.2	112	
8 September K	10-15	502	69	55	8.54	0.001	260	9.6	38	
18 September ^K	09–24	502	188	180	3.94	0.014	265	4.0	187	
19 September ^K	00-07	502	148	120	6.91	0.018	268	6.1	172	
9 October K	20-24	506	221	190	5.30	0.014	260	4.1	159	
10 October K	00-08	506	206	190	3.71	0.015	259	3.1	70	
14 November ^K	00-24	502/506	146	130	5.05	0.009	269	1.2	170	
15 November	00-21	506/502	106	80	6.37	0.004	273	1.4	300	
1 December K	00–12	506	148	100	4.79	0.006	274	1.3	87	
18 September ^K 19 September ^K 9 October ^K 10 October ^K 14 November ^K 15 November 1 December ^K	09-24 00-07 20-24 00-08 00-24 00-21 00-12	502 502 506 506 502/506 506/502 506	188 148 221 206 146 106 148	180 120 190 190 130 80 100	3.94 6.91 5.30 3.71 5.05 6.37 4.79	$\begin{array}{c} 0.014 \\ 0.018 \\ 0.014 \\ 0.015 \\ 0.009 \\ 0.004 \\ 0.006 \end{array}$	265 268 260 259 269 273 274	$\begin{array}{c} 4.0 \\ 6.1 \\ 4.1 \\ 3.1 \\ 1.2 \\ 1.4 \\ 1.3 \end{array}$	187 172 159 70 170 300 87	

Times in the second column are start and end times to the nearest hour. Values of stability, potential temperature, wind speed and wind direction of the free atmosphere are averages between 400 and 1000 m, derived from the 12 UTC radiosonde soundings at Halley. Although Halley is some 50 km distant from the C2 site, it should be representative of the background free atmosphere over C2 during these conditionally sampled periods. The layer between 400–1000 m was chosen as the C2 site is approximately 400 m in altitude. Days where the flow is determined to be primarily katabatically forced are marked with superscript K.

vectors for C2. Note these are 10-second averages, compared to the 15-minute averages of the sodar. For cases of relatively steady flow this discrepancy is unimportant, but for rapidly changing flow it could lead to a mismatch when trying to splice the two observational datasets together to create a wind profile. Certainly the different sampling times must be borne in mind when analysing these data.

Figure 4 shows a well-defined diurnal katabatic flow signature, that is, a lowlevel jet with a monotonic decrease in wind speed with height above it. There is an anticlockwise backing of the wind with height, most sharply between 3 and 30 m where the change in wind direction is typically 30° to 45° . This is indicative of decreasing frictional forcing with height through the boundary layer. The winds at 3 m are close to downslope, i.e. from close to 165° (Table 1), while aloft they are typically south-easterly. There is a clear diurnal signal in the shape of the profiles and the flow strength, with a deeper jet and stronger winds at night and a shallower jet and weaker winds during



Figure 4. Time series of horizontal wind profiles for 23 February 2002 from the Doppler sodar south of Halley. Wind vectors are plotted every 15 minutes, each representing a 15-minute average. Also plotted every hour are wind vectors from an automatic weather station at C2 (see Fig. 1). Tick marks are every hour as labelled, and a scale arrow is shown in the lower left-hand corner.

the day. At this time of year and this latitude $(76^{\circ}S)$ there is a clear diurnal signal in incoming solar radiation which, for clear-sky conditions, is manifest as a diurnal signal in surface air temperature (e.g. see Fig. 5). This leads to a diurnal change in the local katabatic forcing (becoming greater at night) and so a diurnal change in the observed flow. In this case, the daytime decrease in wind speed occurs at all levels, but is more pronounced between 30 and 100 m where winds drop to $\sim 1 \text{ m s}^{-1}$, than at 3 m where there is still a 3–4 m s⁻¹ flow. This suggests that a weak, shallow, katabatic flow persists through the day, gathering speed and depth during the night.

This situation is typical of the summertime katabatic flow cases observed. Indeed, plots of maximum wind speed (of each profile) versus time for all the summertime katabatic cases (November–February) illustrate a clear diurnal cycle, with maximum winds dropping to 2–4 m s⁻¹ between 13 and 16 UTC (not shown). There was a less pronounced cycle for spring/autumn cases (March to April and October) and no discernible diurnal cycle for wintertime cases (May to September). A diurnal signature in katabatic flow has been observed before in AWS observations and numerical simulations (e.g. Gallée *et al.* 1996; Gallée and Pettré 1998) and in tethersonde profiles (e.g. Sorjban *et al.* 1986; van den Broeke *et al.* 1994). There is also some variability in the katabatic flow strength between about 01 and 10 UTC, appearing as an oscillation in the flow with a period of ~3 h. This may be due to some mesoscale variability of the background atmospheric flow encroaching into the katabatic layer, or perhaps due to the advection of differing strengths of katabatic flow over this site.

Figure 5 shows a time series of horizontal wind vectors, potential temperature (θ) , perturbation pressure (p'), total cloud amount and relative humidity with respect to ice (RH_{ice}) from Halley and the three operational AWS sites C2, C3 and C4 (see Fig. 1 for



Figure 5. Time series of winds, potential temperature (θ), perturbation pressure, total cloud amount and relative humidity with respect to ice (RH_{ice}) for 22–25 February 2002 from Halley and automatic weather station sites C2, C3 and C4 as indicated. Hourly observations are shown, with tick marks every hour and long ticks every 6 hours. A scale arrow is shown in the lower left-hand corner of the wind vector panel.

locations) for 22 to 25 February 2002. There is persistent downslope flow at C2 over this period, with a clear diurnal signal. At the higher C3 and C4 sites during the 22nd the winds are more cross-slope and weaker—coincident with higher potential temperatures than at C2 and compared to the rest of the period (when θ is approximately the same at all the AWS sites). These temperature differences are probably due to minor changes in the background flow over the period. The situation of calm conditions at the C4 site during downslope flow at the lower sites was often observed; for example it is implicit in the wind roses of Fig. 2(b). Renfrew and Anderson (2002) show that during katabatic conditions at C2 one of three conditions is possible at C4: calm conditions (as seen at times on 25 February in Fig. 5), low wind speeds from the east (as seen on 22 February) or moderate winds from the east-south-east to south (as seen from 12 UTC 23 February onwards).

At Halley the winds veer from easterly to westerly over 22 to 24 February, under the influence of a weak ridge of high pressure over the southern Weddell Sea. Note that mean-sea-level pressure (m.s.l.p.) analyses from ECMWF (the European Centre for Medium-range Weather Forecasts) were examined for all case-studies. In this case, over Coats Land the synoptic-scale 'background' flow is generally weak and not greatly affecting the observed mesoscale flows that are of interest (m.s.l.p. not shown). This is also apparent in the p' time series, which shows relatively little spreading and low curvature—indicating a relatively 'slack' background pressure field during this period. Note that p' is calculated as the deviation from the monthly mean station pressure, so a spreading of the station p' implies a pressure gradient and local minima correspond to significant low-pressure systems (for further details see Renfrew and Anderson 2002). Figure 5 illustrates that there is little observed cloud and the katabatic flow is relatively dry— RH_{ice} is not saturated at the AWS sites, as is usually the case for a quiescent atmosphere over an ice surface (King and Anderson 1999).

The weak synoptic-scale pressure field, clear skies, and phasing of the winds and θ at the Coats Land sites indicate that the flow here is being katabatically forced. The offset in the initiation of downslope flow over the three AWS sites implies that the downslope katabatic force acts *inhomogenously* down the slope (assuming the same background forcing). In a simple two-layer model of katabatic flow (e.g. see Ball 1956; Mahrt 1982) the katabatic (or buoyancy) forcing can be calculated as:

$$F_{\rm b} = g(\Delta \theta / \theta_0) \alpha,$$

where g is the acceleration due to gravity, $\Delta\theta$ is the potential-temperature deficit, θ_0 is a reference potential temperature and α is the positive slope angle. F_b acts in the downslope direction. Referring to Table 3, the free-atmosphere θ at 12 UTC on 22–25 February is 272 K, thus for 22 February (subtracting the free-atmosphere θ from the AWS θ) $\Delta\theta \approx 4$ K at C2, but $\Delta\theta \approx 0$ K higher up at C3 and C4—implying a katabatic forcing at C2, but none at C3 or C4. A day later, on 23 February, the C3 and C4 temperatures are lower—implying a katabatic forcing there, coincident with the observed downslope winds. In this case the differences in F_b at the three sites explain the different start times for downslope flow.

It is also worth noting that the downslope F_b at C2 is for 12 UTC. Hence for this case there is a local katabatic forcing during the day, which probably explains the persistent weak katabatic flow observed at the 3 m level. Inspection of the θ time series shows positive $\Delta \theta$ values at C2 throughout the period 22–25 February (Fig. 5), suggesting that this is the situation for this entire period. As noted earlier, at this time of year there is a clear diurnal signal in solar radiation and hence for surface air temperature (given clear-sky conditions). Surface energy-balance reasoning would suggest that the diurnal



Figure 6. A downslope cross-section of horizontal and vertical winds as a function of time and height for 23 February 2002 from the Doppler sodar south of Halley. Wind profiles are plotted every 15 minutes, each representing a 15-minute average. A scaling arrow is shown in the top right-hand corner. The horizontal velocities are scaled by the slope angle (0.05), such that a slope-parallel flow will have an angle of 45° from horizontal.

cycle near the surface is greater than that aloft, so one would expect a diurnal cycle in F_b and a consequent diurnal cycle in katabatic flow: weak flow during the day, stronger and deeper flow at night.

Figure 6 shows a time-height cross-section of wind vectors in the downslope vertical plane from the Doppler sodar for 23 February 2002, i.e. the same period as Fig. 4. The vector components are scaled by the slope ratio (0.05) so that for flows parallel to the surface the vectors point at 45° to the horizontal. The flow is in a downslope direction everywhere, but much stronger near the surface, indeed becoming almost stationary in the horizontal at 115 m and above. This suggests the katabatic flow has a depth of approximately 100 m in this case. There is generally descent into the katabatic layer as one would expect from large-scale continuity constraints, indeed the flow is often approximately parallel to the surface. The stronger horizontal winds are generally coincident with periods of stronger descent, such as around 01-03 UTC and 08–09 UTC. Between 16 and 18 UTC (\approx 14 and 16 local time) the downslope flow ceases and there are dramatic upward velocities. Assuming the flow upslope of this location persists, as suggested by Fig. 5, then the horizontal flow cessation must lead to convergence and hence ascent. In this summertime case the cessation of the katabatic flow is linked to the diurnal cycle and a weakening of the potential-temperature deficit (the maximum near-surface temperature during clear-sky conditions is around 14-18 UTC—see Fig. 5). The abrupt cessation of katabatic flows has been observed before in surface pressure, temperature and horizontal wind data (e.g. Pettré and André 1991). Here it is clear that the cessation occurs throughout the boundary layer and there is a dramatic vertical velocity response that is coherent with height. The observed upward velocities are typically 0.5 m s^{-1} and as large as 1 m s^{-1} .



Figure 7. Time series as Fig. 4, but of horizontal wind profiles for 14 August 2003.

The switch from a $5-8 \text{ m s}^{-1}$ downslope flow to a largely vertical velocity may be related to a hydraulic (or 'katabatic') jump, although there is no direct evidence of a jump from the AWS observations (Fig. 5). Perhaps due to their relatively low temporal resolution (i.e. hourly), or because these are relatively weak downslope flows, any katabatic jump will also be weak. Katabatic jumps have been observed as neardiscontinuities in horizontal wind speed and pressure (e.g. Pettré and André 1991). They have been seen in recent idealized modelling experiments for the Coats Land region by Renfrew (2004) and Yu et al. (2005). Renfrew (2004) found internal gravity waves being triggered towards the foot of the Coats Land continental slope, close to the C2 site, as the katabatic flow went from weakly supercritical to subcritical in response to cold air building up on the Brunt Ice Shelf and damming the flow. Yu et al. (2005) examined katabatic jumps in detail, finding their location to be a function of the depth and strength of this cold-air pool. Yu et al. found the \sim 1 hPa pressure changes associated with the katabatic jumps was better explained by a Bernoulli theory analysis than by a simple hydraulic theory analysis. The three-dimensional wind observations in this case are consistent with those modelled in the above studies, and therefore suggest that the strong vertical acceleration may well be associated with a katabatic jump, and thus may be capable of triggering internal gravity waves. Similar patterns of a dramatic ascent following flow cessation are clear on several other days (not shown). A more detailed study of internal gravity waves triggered by katabatic flows is in progress.

(b) A wintertime katabatic flow case

Horizontal wind profiles from a case of moderate wintertime katabatic flow on 14 August 2003 are illustrated in Fig. 7. Here the strongest observed winds are at the 3 m (AWS) level. Again there is generally a monotonic decrease in wind speed and an anticlockwise backing with height that is strongest in the surface layer (between 3 and

30 m). The winds aloft are rather weak compared to the near-surface winds, suggesting a very shallow katabatic flow with a jet maximum between 3 and 30 m.

In Fig. 8 horizontal winds, θ , p', cloud amount and RH_{ice} are shown for 13–15 August 2003. The surface wind pattern is rather complex, and reflects the presence of a slow-moving low-pressure system to the north in the Weddell Sea, as suggested by the low p', the spread of p' over the stations, and the sharp rise from a local minima during the 14 August as the low moves past (m.s.l.p. analyses not shown). Its movement is also reflected in a veering of the surface winds and the relatively warm and cloudy conditions at Halley.

During 14 August the winds at C2 are steady and downslope. They are apparently katabatically forced in part as it is relatively cold there; indeed, using data from Table 3 implies $\Delta\theta \approx 9$ K suggesting a substantial katabatic forcing. However, the winds are also influenced by the low-pressure system to the north. At C3 and C4 the flow is more across-slope, indeed somewhat upslope later in the day. It is also relatively warm compared to C2, such that $\Delta\theta \approx 0$ K—there will be no katabatic forcing—and RH_{ice} is 100%. This suggests that higher on the Coats Land slopes the synoptic-scale flow is dominating. In this case it seems that the downslope flow observed at C2 is a highly localized response to a local katabatic forcing.

4. THE VERTICAL STRUCTURE OF PRIMARILY KATABATIC FLOW

The autonomous Doppler sodar system provides, for the first time, continuous profiling of katabatic flows all the year round from an Antarctic coastal slope. Here an analysis of the vertical structure of these katabatic flows is described. In order to carry out this analysis, a categorization of the observation periods is useful. This has been achieved through a thorough case-by-case assessment of each observation period to determine whether the flow is primarily katabatically or synoptically driven. As discussed recently in a series of observational and modelling papers by various authors (e.g. Parish and Cassano 2001, 2003a,b; Renfrew and Anderson 2002; Van den Broeke *et al.* 2002) apparently katabatic flow can simply be a synoptically forced flow that is moulded by the topography to be downslope in direction.

Here we have subjectively defined a subset of our observations as 'primarily katabatic flows' by examining: (i) surface observations at Halley and Coats Land, (ii) satellite imagery, and (iii) m.s.l.p. analyses, and adapting criteria put forward by Renfrew and Anderson (2002). Observational periods were categorized as being *primarily katabatically driven* if there were: essentially clear skies (low amounts of cloud observed at Halley and clear satellite imagery); little influence from synoptic-scale weather systems (small p' differences and changes at the AWS stations; and an area of weak pressure gradients in the analyses); and a significant potential-temperature deficit (determined from near-surface AWS and free-atmosphere radiosonde observations—as illustrated in the previous section). The primarily katabatic flow periods make a subset of 16 days and 805 soundings from the 28 days and 1626 soundings listed in Table 3, where they are marked by a superscript K. The rest of this paper focuses on these observations.

Both the observational periods described in the previous section were primarily katabatic flows; as an illustration of the vertical structure, Fig. 9 shows wind speed, wind direction and vertical velocity (w) against height, plus downslope horizontal velocity (u) versus across-slope horizontal velocity (v) for hourly observations combined from the Doppler sodar and AWS on 23 February 2002 (the same period as Figs. 4 and 6). The classic elevated jet shape associated with katabatic flows is clear in a number of the wind speed profiles, but certainly not all. In these the jet maximum is at the lowest



Figure 8. Time series as Fig. 5, but for 13–15 August 2003.



Figure 9. Hourly wind profiles from 23 February 2002 from the combined Doppler sodar and automatic weather station observations south of Halley. Shown are: (a) wind speed and (b) wind direction against height; (c) downslope horizontal velocity (u) against across-slope horizontal velocity (v); and (d) vertical velocity (w) against height. In (c) the lowest-altitude observation is marked with a + sign.

Doppler sodar observation, in this case 30 m. At other times the maximum wind speed that is observed is at the AWS height. Referring back to Fig. 4, one can see that many of these profiles are during the afternoon, when the katabatic flow aloft has ceased but there is still a very shallow downslope wind. The profile of wind direction with height is remarkable consistent through the day, despite the changes in wind speed. There is backing of about 40–60° between the observations at 3 and 30 m that continues through the boundary layer and is a result of weakening frictional effects with height. Figure 9(d) shows that for most profiles the strongest descent is in the lowest layers, typically -0.2 m s^{-1} , although profiles with ascent are also evident.

For each profile we calculated the observed maximum wind speed (U_{max}) and the height at which this occurs (z_{max}) . For katabatic flows following the classic shape of an elevated low-level jet, the jet maximum would have speed U_{max} at a height z_{max} . However, Fig. 9 makes it clear that, in this case, the jet profile is only coarsely resolved by the Doppler sodar and AWS. The jet changes rapidly over the lowest ~100 m and, given that the Doppler sodar employs volume-averaging over layers of 10–20 m thickness, this means some detail is unresolved; furthermore, at times the jet maximum appears to fall in the gap between 3 and 30 m, i.e. between the AWS and the lowest



Figure 10. Scatter plot of maximum wind speed (U_{max}) versus its height (z_{max}) for all the wind profiles measured over the slope south of Halley, where the flow is categorized as primarily katabatically driven (805 profiles). Maxima determined from the Doppler sodar data only are marked by dots, while maxima from profiles where the automatic weather station data are included (a subset of 188 profiles) are marked by open circles.

Doppler sodar range gate (20–40 m for this period). The flow structure is captured more accurately for observing periods with the higher-resolution Doppler sodar setting (cf. Table 3), however, as mentioned earlier these periods compromise on range. These resolution and observing gap constraints are a limitation to this dataset.

Figure 10 shows U_{max} versus z_{max} for all profiles in the primarily katabatic flow category. It is clear that z_{max} is frequently in the range 3–50 m for a range of U_{max} values, which is consistent with the picture of an archetypal low-level jet. The greatest values of U_{max} (>10 m s⁻¹) usually have z_{max} between 25 and 60 m, on average ~40 m. For the majority of katabatic flow profiles, z_{max} ranges between 3 to 80 m. Although there are many observations with z_{max} at higher altitudes, these seem to vary in both height and wind-speed, suggesting no persistent vertical structure with these characteristics. Observations where $z_{\text{max}} = 3$ m seem to be limited such that U_{max} is between 3 and 9 m s⁻¹. Profiles where $U_{\text{max}} < 3$ m s⁻¹, i.e. when the entire boundary layer is quiescent, tend to have z_{max} spread throughout the vertical range; while profiles with $U_{\text{max}} > 9$ m s⁻¹ tend to have z_{max} confined to 25–60 m, as mentioned above.

Standard surface-layer theory would suggest that when $z_{max} = 3$ m, in reality the highest wind speed is probably somewhere in between 3 m and the height of the lowest Doppler sodar level for that case (i.e. 20–30 m or 20–40 m, depending on the sodar setting). In other words, the jet maximum falls in the gap with no observations in our vertical profiles. This is born out by the fact that when $z_{max} = 3$ m, over 50% of the

associated profiles have their second highest wind speed at the lowest Doppler sodar level; while the remainder have their second highest wind speed spread throughout the vertical range.

The same plots for subsets of the primarily katabatic flows from winter (April–September; 230 profiles) and summer (October–March; 575 profiles) have also been examined (not shown). All the strongest low-level jets (>10 m s⁻¹) occur in winter, and 95% of all winter z_{max} values are below 100 m; by contrast the summer values span the vertical range (see Fig. 10). In winter when $z_{\text{max}} = 3$ m, U_{max} is concentrated between 6 and 9 m s⁻¹, suggesting that for these very shallow katabatic flows there is a threshold wind speed which wintertime katabatic flows generally attain.

To illustrate mean, or archetypal, katabatic wind profiles the primarily katabatic flow observations have been divided into different flow strengths using their maximum wind speed (U_{max}) . Profiles of the mean and the mean plus and minus one standard deviation for each flow strength are illustrated in Fig. 11. The profiles have been binned into weak, moderate and strong flows: $0 \le U_{\text{max}} \le 4 \text{ m s}^{-1}$ (solid line with dots); $4 < U_{\text{max}} \le 8 \text{ m s}^{-1}$ (dashed line); and $U_{\text{max}} > 8 \text{ m s}^{-1}$ (solid line), respectively. The bins contain 198, 436 and 109 Doppler sodar profiles and 19, 135 and 34 AWS observations, respectively. The Doppler sodar observations are linearly interpolated onto a 5 m resolution vertical grid to allow for the different sodar settings, and then averaged for each height. If less than 10% of the possible observations are available at that height, then an average is not calculated. This quality-control check is to stop a few profiles dominating the average and, effectively, acts to limit the range of the mean profilesas is apparent in Fig. 11. At a height of 3 m the mean and mean plus and minus one standard deviation of each bin for the AWS data are plotted. Many fewer observations make up these values (188 compared to 805) due to the hourly temporal resolution of the AWS compared to the 15-minute resolution of the Doppler sodar. In including these data on the same plots we are, in essence, interpolating the AWS data in time. Note, mean profiles of the matched Doppler sodar and AWS data only, were also examined and these are qualitatively similar to those of Fig. 11, suggesting the combination of the Doppler sodar only and the spliced profiles does not distort the illustrated profiles. However, the 3 m values are plotted as a separate point to illustrate the gap in observations between the AWS and the lowest Doppler sodar range gate.

The mean katabatic flow profiles show systematic differences for the different flow strengths. The weak flows ($0 \le U_{\text{max}} \le 4 \text{ m s}^{-1}$) have a wind speed that is approximately constant with height. There is, on average, a backing in the wind direction with height, the flow being more downslope nearer the surface.

The moderate flows ($4 < U_{max} \le 8 \text{ m s}^{-1}$) have a monotonically decreasing wind speed with height, with little evidence of a low-level jet. However, the AWS observations are, on average, higher than the lowest Doppler sodar-level observations. Examining individual profiles (e.g. Figs. 4, 7 and 9) we see that this reflects an averaging over times when $z_{max} \ge 25$ m (and there is a resolved low-level jet), and when $z_{max} = 3$ m and the flow is weak aloft but maintains a certain minimum speed near the surface (around 4 m s⁻¹ in the case illustrated in Fig. 9). This suggests that *on average* there is a windspeed maximum somewhere between 3 and 25 m, i.e. a very shallow low-level jet, which unfortunately falls in the gap in observations between the AWS and the Doppler sodar. This interpretation is corroborated by summertime observations of weak to moderate katabatic flows on the Breidamerkurjökull glacier, Iceland, by Parmhed *et al.* (2004). In their mast and balloon profiles the height of observed low-level wind maxima ranged from 2.5 to 13.0 m, with jet wind speeds ranging from 3.3 to 10.1 m s⁻¹. Motivated by individual profile observations (e.g. Fig. 9) and other studies (e.g. Parmhed *et al.* 2004;



Figure 11. Wind profiles for primarily katabatically driven flows over the slope south of Halley, showing lines for the mean, and the mean plus and minus one standard deviation: (a) wind speed, (b) vector-mean wind direction (mean profiles only for clarity), (c) downslope horizontal velocity (u), and (d) across-slope horizontal velocity (v). The data have been binned into weak, moderate and strong flows: $0 \le U_{\text{max}} \le 4 \text{ m s}^{-1}$ (solid line with dots); $4 < U_{\text{max}} \le 8 \text{ m s}^{-1}$ (dashed lines and stars) and $U_{\text{max}} > 8 \text{ m s}^{-1}$ (solid lines and open circles), respectively, where U_{max} is the observed maximum wind speed. The automatic weather station data for each bin have been plotted at the 3 m level.

Haiden and Whiteman 2005), we suggest that the jet maximum is likely to be at most $\sim 1 \text{ m s}^{-1}$ stronger than that measured at 3 m. The mean plus and minus one standard deviation profiles closely mimic the shape of the mean profile, suggesting that there is little change in variability with height (the standard deviation is around 2 m s⁻¹ at all levels). In other words, these katabatic flows consistently look like the illustrated mean profile. There is a backing in the wind direction with height: at the AWS level the flow

is close to downslope ($\sim 165^{\circ}$), backing to approximately easterly by 150 m above the surface.

The strongest flows ($U_{\text{max}} > 8 \text{ m s}^{-1}$) illustrated in Fig. 11 are better resolved by our observing system. The mean wind speed profile has a pronounced low-level jet at 30–35 m. Above the jet maximum the wind speed falls away approximately linearly; while below the jet maximum the mean AWS observation is only $\sim 1 \text{ m s}^{-1}$ below the jet maximum value. This suggests that, on average, there is a layer of approximately constant wind speeds between 3 and 25 m. However, individual profiles (e.g. Fig. 9 and similar figures for other days) suggest that sometimes this is the case, but at other times the jet has a more pronounced profile (illustrated by the mean plus one-standarddeviation curve) or is strong and shallow. The wind direction is somewhat more crossslope for these stronger flows compared to the moderate strength flows, reflecting greater Coriolis and frictional forces as a result of the higher wind speeds.

The mean wind profiles illustrate that for strong winds the katabatic flow clearly has a well-defined low-level jet. However, for the moderate winds the mean profile appears to comprise resolved low-level jets and poorly resolved low-level jets suggested by a maximum at the level of the AWS. The mean AWS values are higher than one might expect from looking at individual profiles, because there appears *always* to be a downslope flow at this height during these primarily katabatically driven periods. In contrast, aloft the katabatic flow can fade away to near-calm conditions (e.g. Fig. 4).

Panels of downslope (u) and cross-slope (v) velocities are also included in Fig. 11. It can be inferred that a low-level maximum in u exists between 3 and 25 m for both the moderate and strong flows. There is a steep increase in v with height between 3 and 30–40 m. Above that v slowly decreases with height, or is approximately constant, for the weak and moderate flows; it has a more distinctive diffuse jet structure for the strong flows. It is worth noting that for the weak and moderate mean profiles u tends to an approximately constant value of 0–1 m s⁻¹ with height. In this sense, one can state that these katabatic flows directly influence only the lowest ~150 m of the atmosphere. There are insufficient observations to comment on this for the strong-flow category.

Normalized mean profiles, for example U/U_{max} versus z/z_{max} , were also calculated (not shown). It was found that binning by U_{max} (as above) the profiles were not self-similar; rather, profiles with a high U_{max} had a broader jet structure, while profiles with a low U_{max} had a more tightly confined jet structure.

Renfrew (2004) details idealized numerical simulations of katabatic flows over Coats Land using a non-hydrostatic numerical weather prediction model. The simulations are initialized using climatological atmospheric and surface temperatures, and at rest; in other words, the 'background' synoptic-scale flow is assumed to be zero. Further details of the model set-up can be found in Renfrew (2004). Some details particularly pertinent to these katabatic flow simulations are: a model of resolution 2 km by 2 km by 5 m (with stretching in the vertical), a surface-layer scheme following Louis (1979) and Cassano et al. (2001), and a prognostic turbulence scheme for diffusion in the vertical. In the simulations radiative forcing leads to a cooling and the development of a quasi-steady downslope 'pure' katabatic flow. Figure 12 shows soundings at 12, 24, 36 and 48 h at the C2 site (the location of the Doppler sodar) from the control simulation described in Renfrew (2004). The dots in the 48 h sounding illustrate the model's vertical levels. The potential-temperature deficit is around 15 K, the maximum wind speed \sim 7 m s⁻¹ and the low-level jet is around 30 m above the model surface. Overlaid are mean and mean plus and minus one-standard-deviation profiles of a subset of the primarily katabatic flow observations where: $6 < U_{max} \le 8 \text{ m s}^{-1}$ and $20 \le z_{max} \le 60 \text{ m}$ (106 profiles). This subset is chosen so that the wind speed and height of the observed



Figure 12. Numerical model soundings at the automatic weather station (AWS) C2 south of Halley for simulation times 12, 24, 36 and 48 h as indicated, of: (a) potential temperature (θ), (b) wind speed, (c) wind direction, (d) downslope horizontal velocity (u), (e) across-slope horizontal velocity (v), and (f) vertical velocity (w). Overlaid bold lines show the mean (full line), and mean plus and minus one-standard-deviation (dashed lines) wind profiles for a subset of the primarily katabatic flows with $6 < U_{max} \le 8 \text{ m s}^{-1}$ and $20 \le z_{max} \le 60 \text{ m}$, where U_{max} is the measured wind speed maximum, and z_{max} the height of the maximum wind. Data from the AWS (at 3 m) have been plotted as squares.

low-level jet matches that of the control simulation, and hence other features of the simulated katabatic flow can be meaningfully compared to the observations.

The simulated wind speed profiles generally compare well with the observations. Over time in the simulation there is a general broadening of the low-level jet, as momentum is mixed upwards. The soundings at 36 and 48 h correspond most closely in shape to the mean profile, although the more focused jet shapes at 12 and 24 h are well within the range that is observed. In contrast, the simulated 3 m wind speeds are all well below the observations, i.e. the simulation does not capture the rapid increase in wind speed near the surface. This problem was also noted in Renfrew (2004), where comparisons with mean AWS observations were made. In that study it was suggested that either the model's surface-layer parametrization was at fault or there was a sampling

problem in the way that the average wind speeds were calculated. The comparison in Fig. 12 rules out any such sampling problems. Indeed, it is clear from comparing the model profiles to those in Figs. 4, 7, 9, 11 and 12 that the katabatic jet often reaches its maximum value over these lowest few metres, a feature not captured by this simulation, nor indeed any others carried out by Renfrew (2004), e.g. those where the ratio of the momentum to heat diffusion coefficients was tuned. These results confirm that further work on parametrizing the model's surface layer for stable conditions is required.

The simulated wind direction generally compares well with the observed wind direction, especially at 3 m. The simulated profiles back more steeply than the observations—probably a reflection of the fact that on average there is a light background wind in the observations (easterly aloft, more south-easterly at the surface) which is not in the model. This missing background wind also affects the simulated u and v components, which are otherwise generally well-simulated. There are some differences aloft where the model simulates u tending to zero, while in reality an easterly background wind will project approximately equally onto the down-slope and cross-slope directions. The poor simulation over the first few model levels is manifest as an underestimate of magnitudes of both u and v at 3 m. Indeed the simulated u jet is too high and strong, while the simulated v flow does not increase quickly enough over the lowest 30 m, but corresponds well from ~50 m upwards.

The simulated descent into the katabatic layer compares well with that observed the minimum values are about the correct height and magnitude. There is clearly more variability in the observations, with the mean plus one-standard-deviation profile largely positive. This reflects both the turbulent nature of katabatic flows and the dramatic ascent that occurs upon the cessation of katabatic flows (e.g. Fig. 6).

In summary, the simulated pure katabatic flows generally compare well to the mean primarily katabatic flow observations; the main difference is that the model winds are too weak over the first few model levels. The overall structure is well modelled, if one allows for a residual background flow in the observations that is not included in the model simulation.

5. CONCLUSIONS

An analysis of subjectively determined katabatic flows in Coats Land, Antarctica, making use of vertical wind profiles from an autonomous Doppler sodar system has highlighted a number of interesting features. There is a systematic change in the shape of the low-level katabatic jet with wind speed. On average, stronger katabatic flows, with wind speed maxima of typically 8–10 m s⁻¹, are deeper with a jet maximum at \sim 20–60 m altitude; moderate katabatic flows, with wind speed maxima of typically 4–8 m s⁻¹, are shallower with a jet maximum more often between 3 and 30 m. The strongest katabatic flows have a greater cross-slope component, consistent with a greater Coriolis force and frictional drag. For all katabatic wind profiles there is a backing in wind direction with height over the lowest \sim 100 m, consistent with a frictional forcing at the surface.

During summer there is a clear diurnal signature in the katabatic flow at all heights. It is more pronounced at 20 m and above, where the flow often ceases entirely, whereas at the surface there always appears to be some weak $(2-4 \text{ m s}^{-1})$ katabatic flow. A dramatic deceleration of the katabatic flow is followed by strong vertical acceleration—with vertical velocities reaching $0.25-1 \text{ m s}^{-1}$. Such cessation events may lead to katabatic jumps, analogous to hydraulic jumps, as the flow changes from supercritical to

subcritical down the slope; this was seen in recent non-hydrostatic numerical modelling studies of katabatic flow in Coats Land (Renfrew 2004; Yu *et al.* 2005).

Simulated wind profiles from the Renfrew (2004) modelling study compare well to mean profiles of a conditionally sampled subset of the katabatic flow observations. The structure and direction of the observed flows are well simulated, especially if one allows for a weak background flow in the observations that is not present in the simulations. The one significant difference is that the model does not capture the rapid increase in wind speed over the lowest ~ 10 m, i.e. the wind speed is too weak for the first few model levels.

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